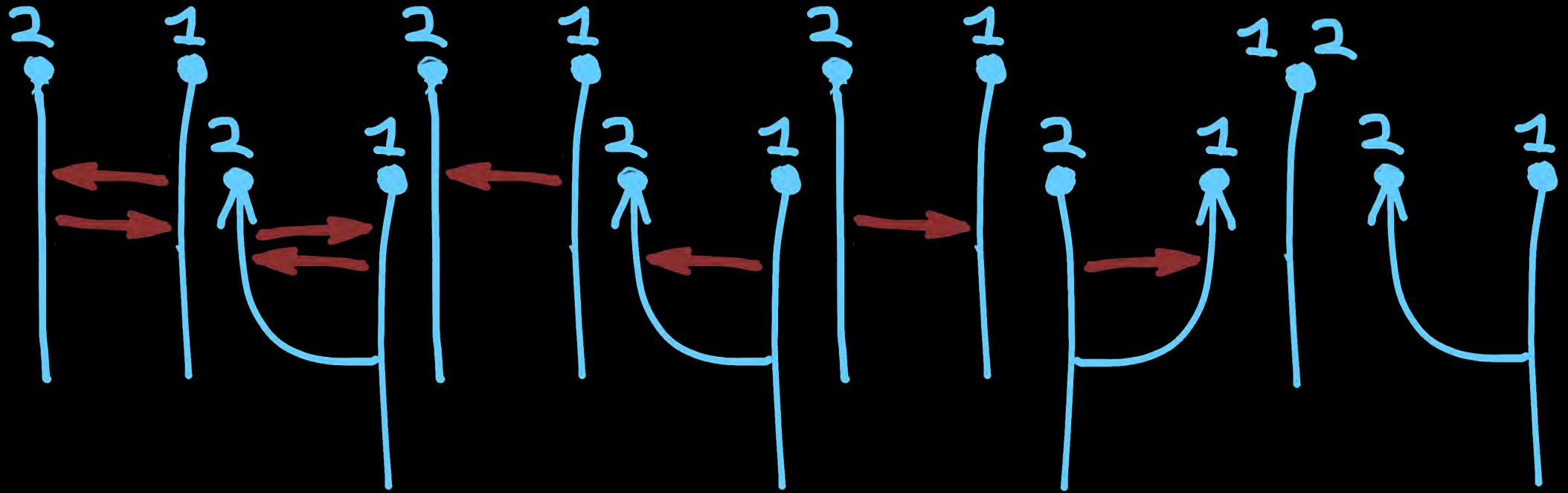
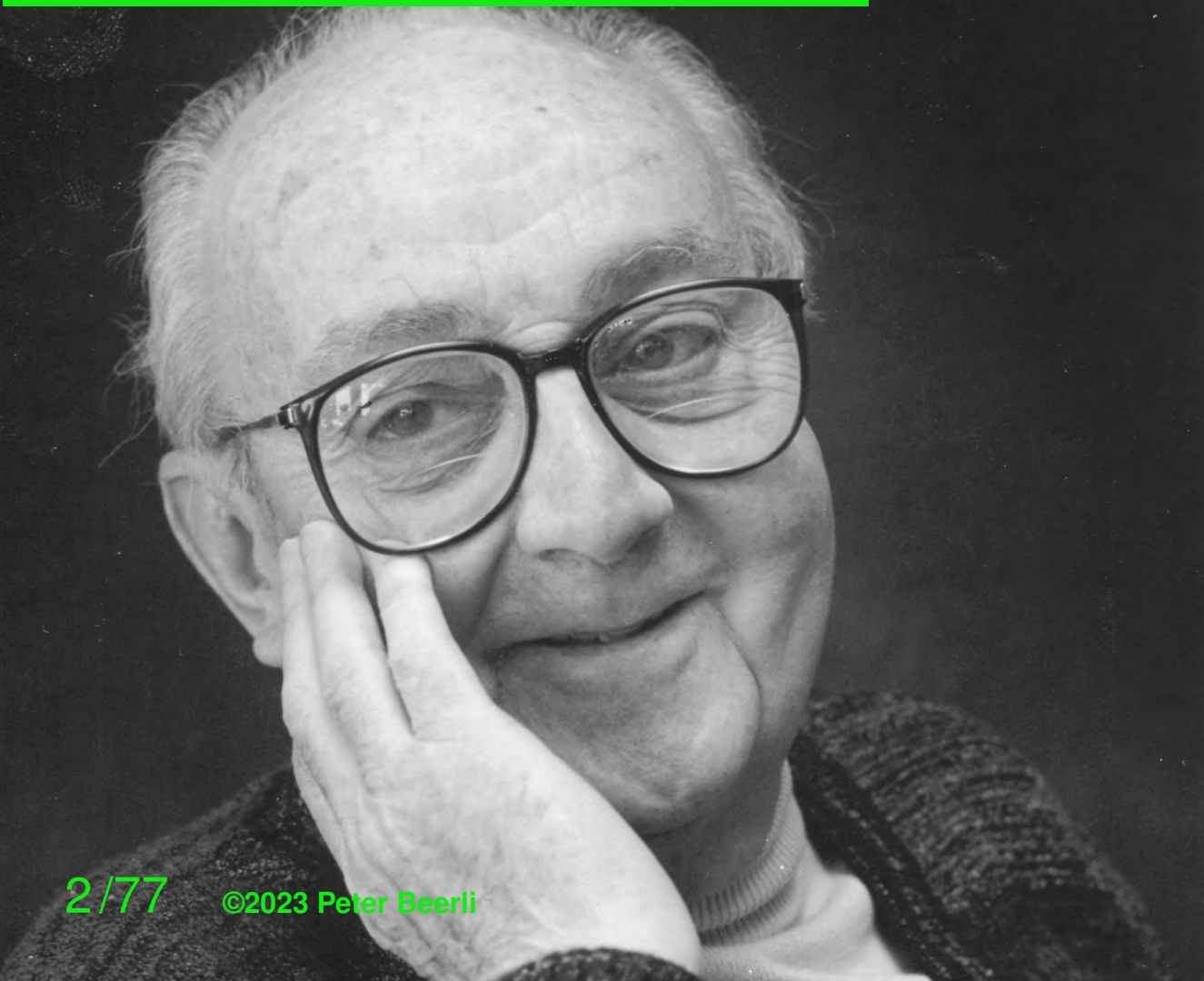


All models are good, but only some are useful



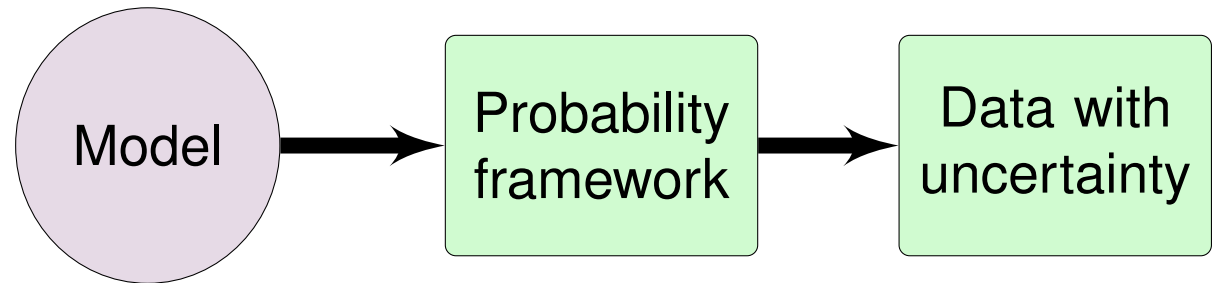
On models



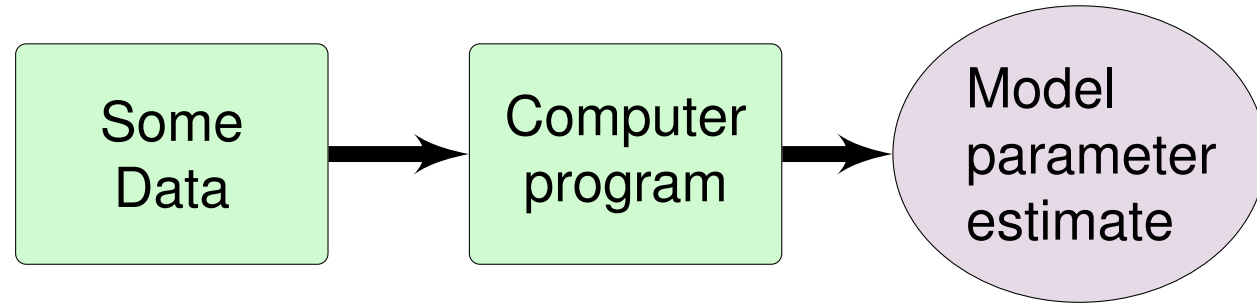
Essentially, all models are wrong, but some are useful.

Box, George E. P.; Norman R. Draper (1987). Empirical Model-Building and Response Surfaces, p. 424, Wiley.

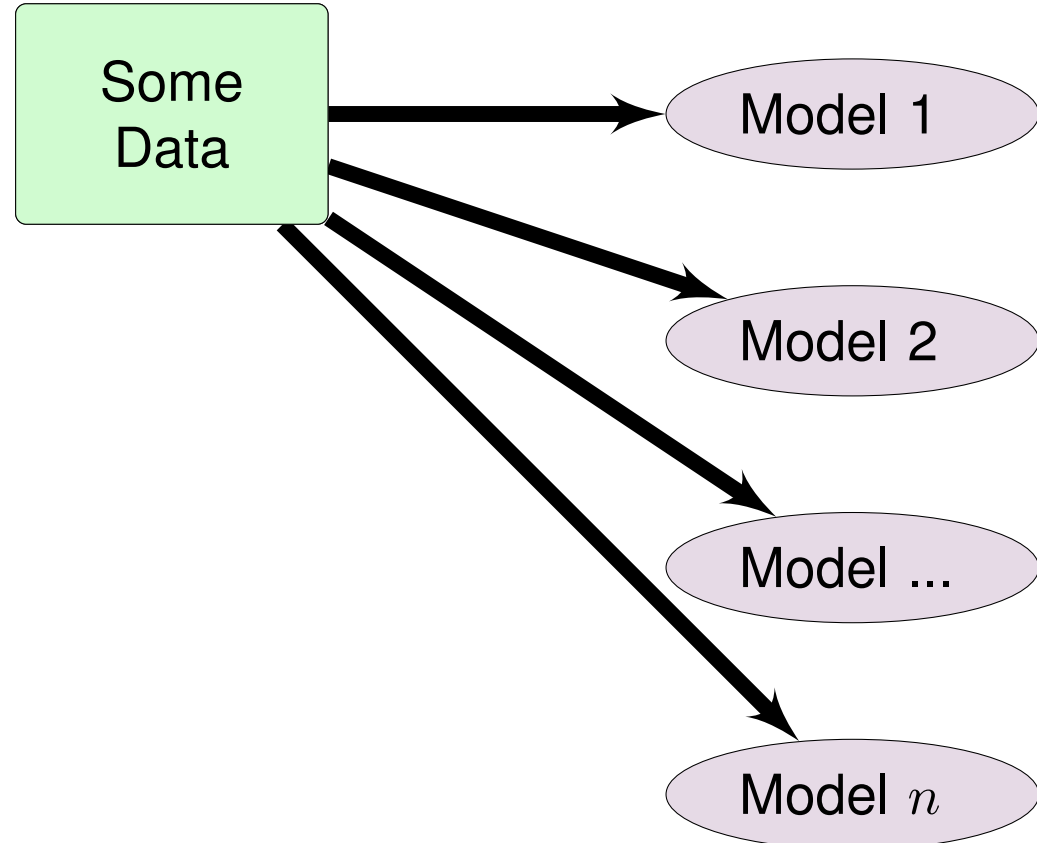
On models and data



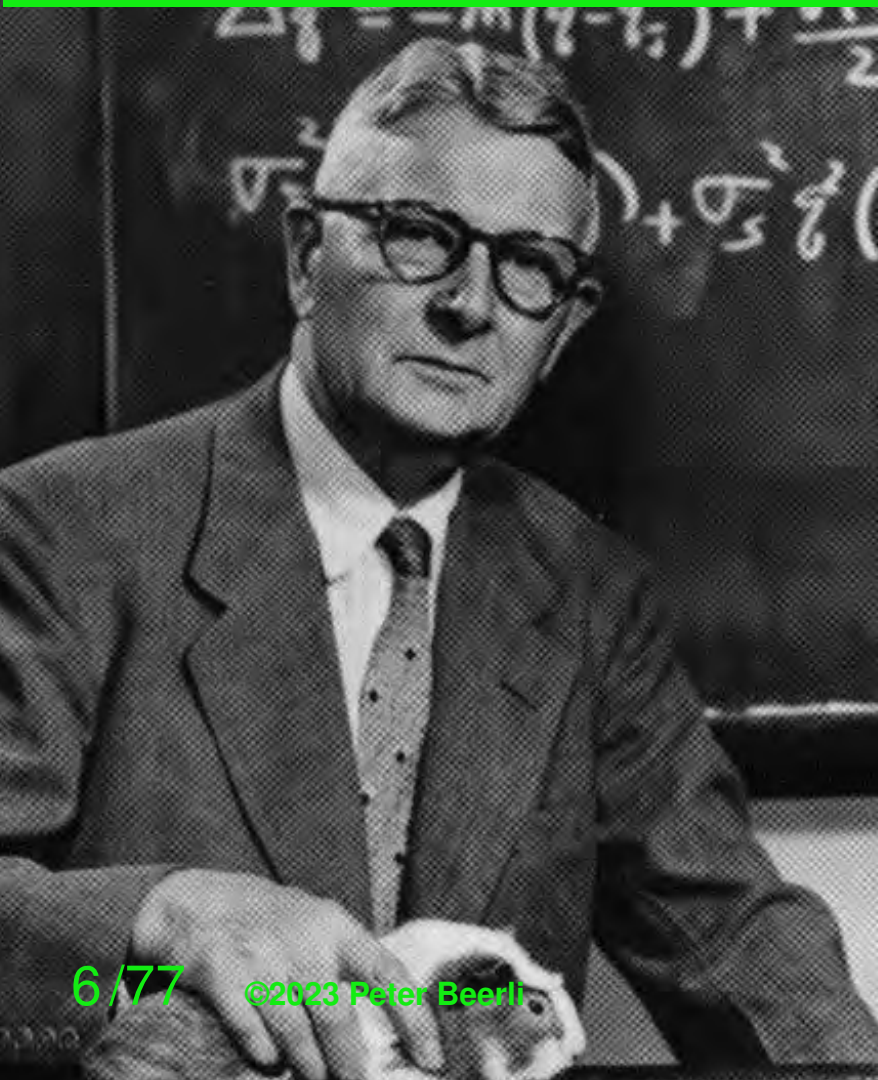
On data and models



On models and data

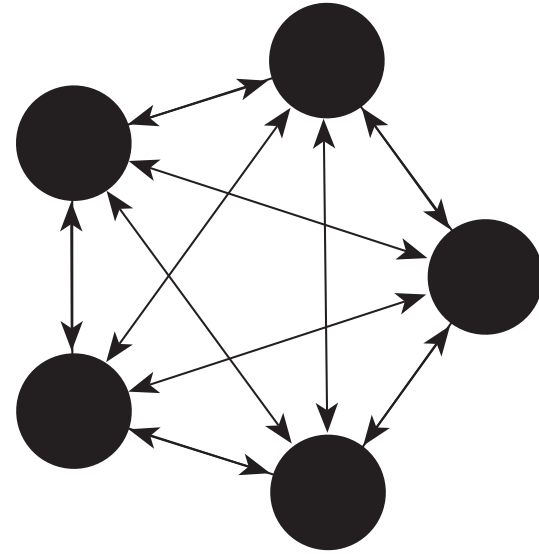


Population genetics models



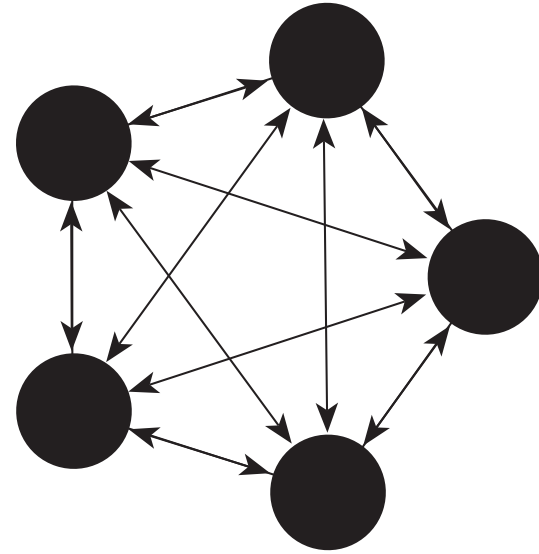
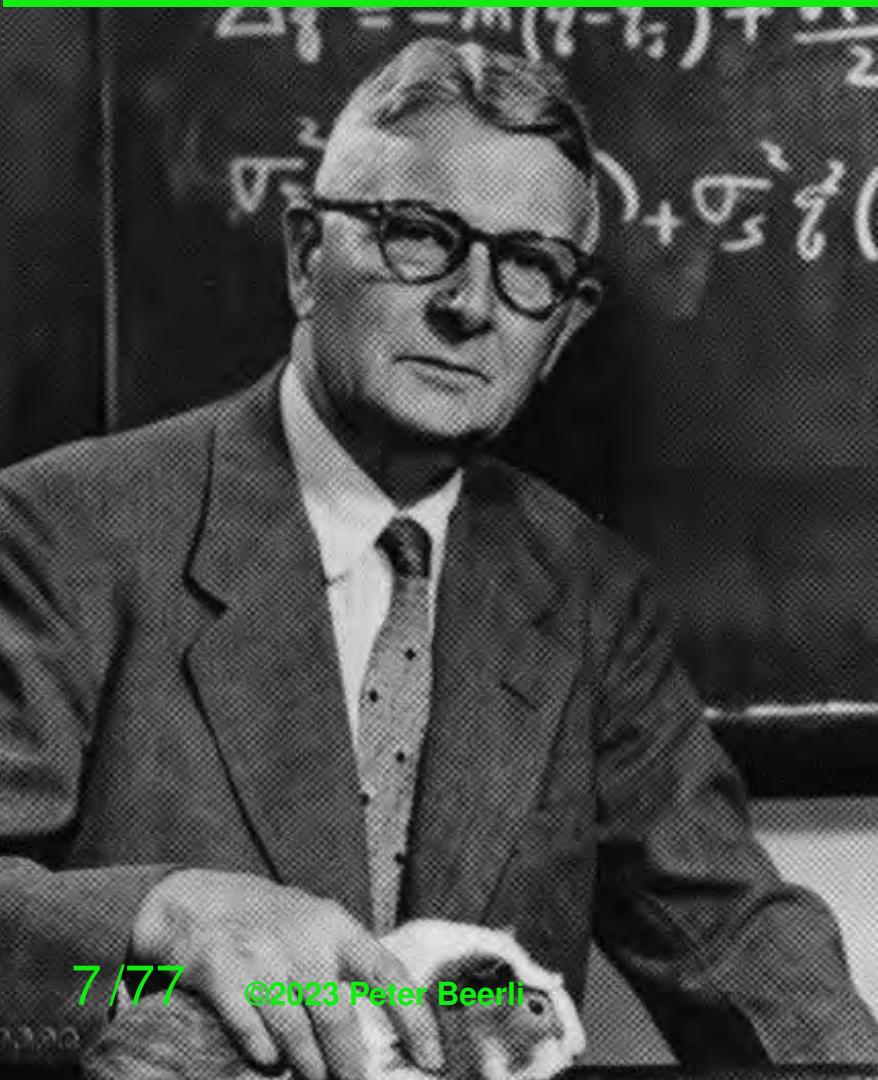
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Theoretical Biologist: Sewall Wright

Population genetics models



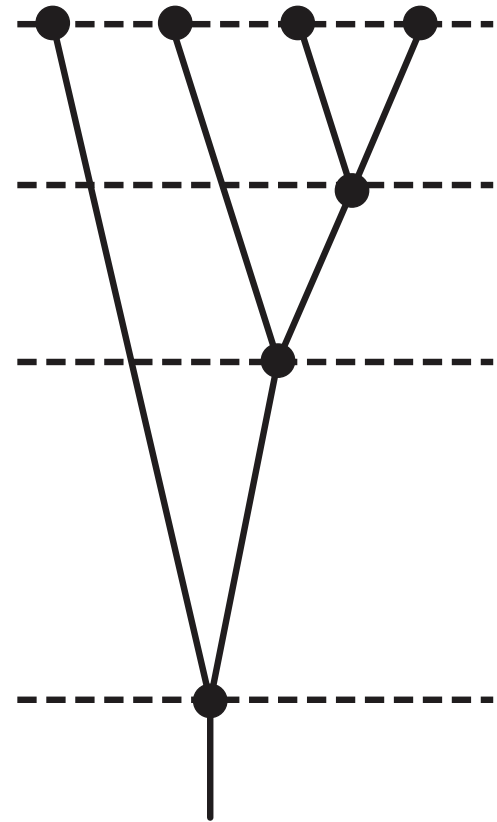
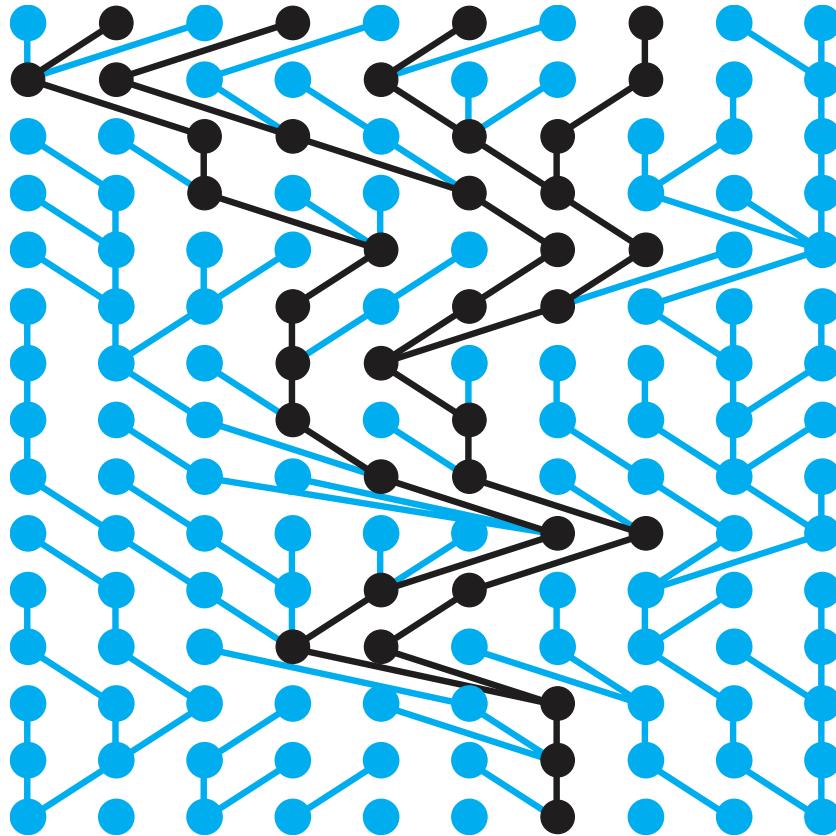
$$F_{ST} = \frac{\sigma^2(p)}{p(1-p)} \simeq \frac{H_T - \bar{H}_S}{H_T}$$

$$F_{ST} \approx \frac{1}{4Nm+1}$$

$$Nm \approx \frac{1}{4} \left(\frac{1}{F_{ST}} - 1 \right)$$

Theoretical Biologist: Sewall Wright

Population genetics models

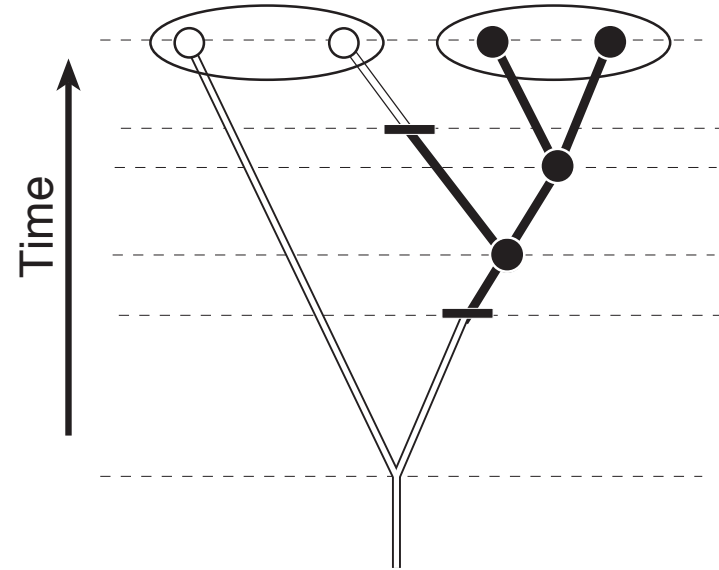
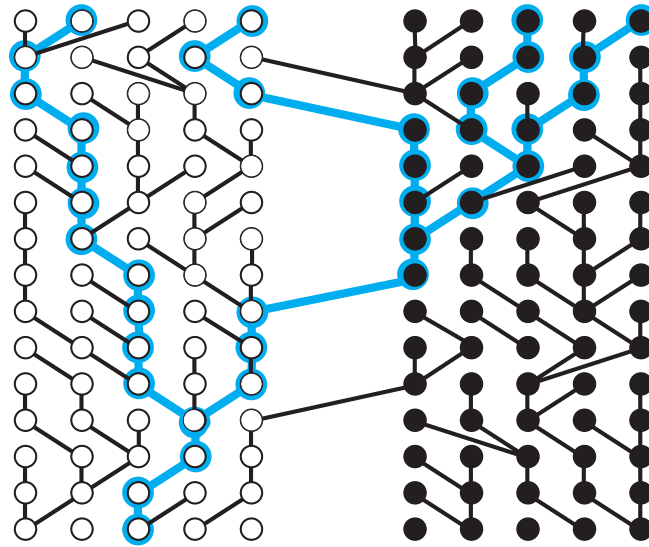


Population genetics models



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Theoretical Biologist: Dick Hudson

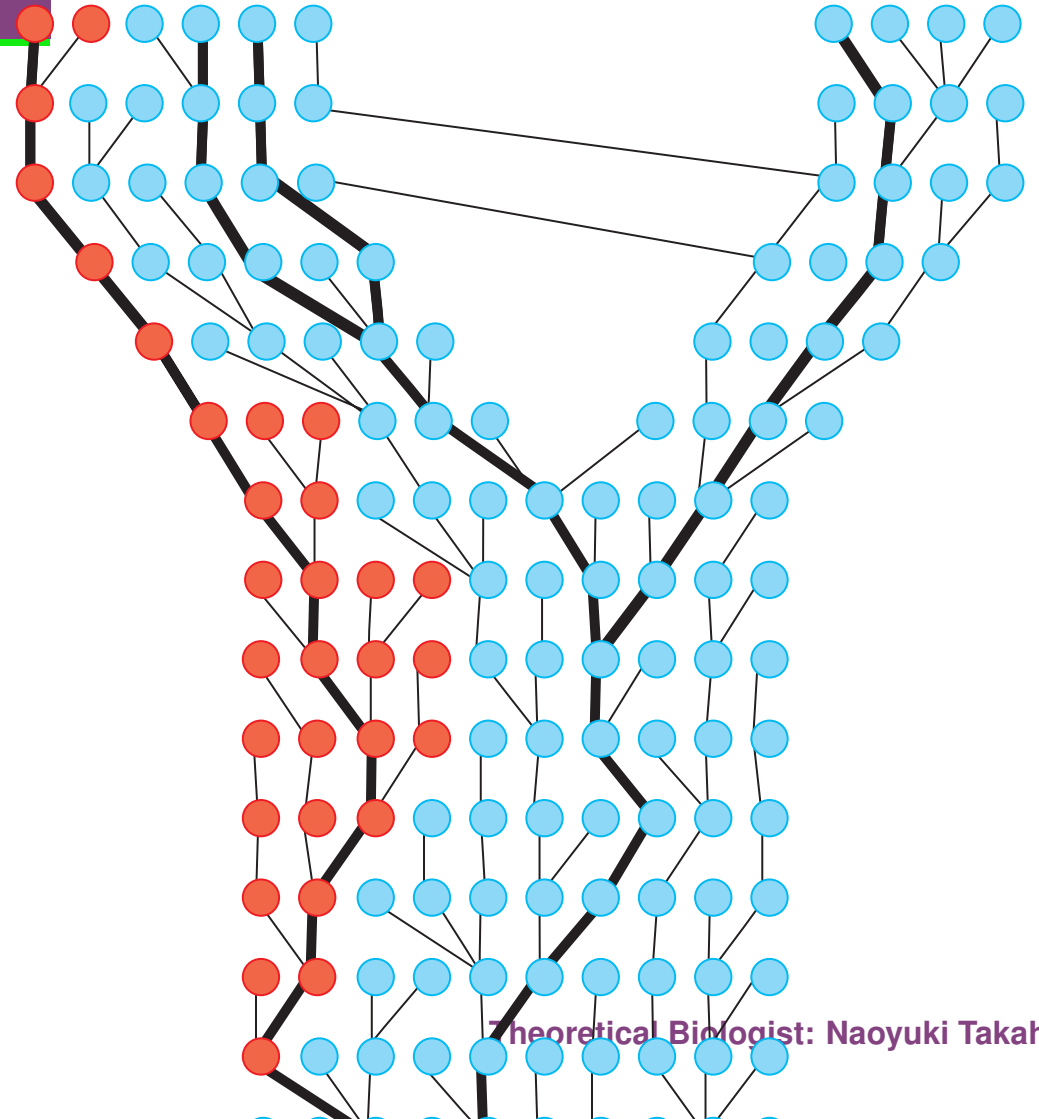
Population genetics models



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Time ↑



Theoretical Biologist: Naoyuki Takahata

Population models

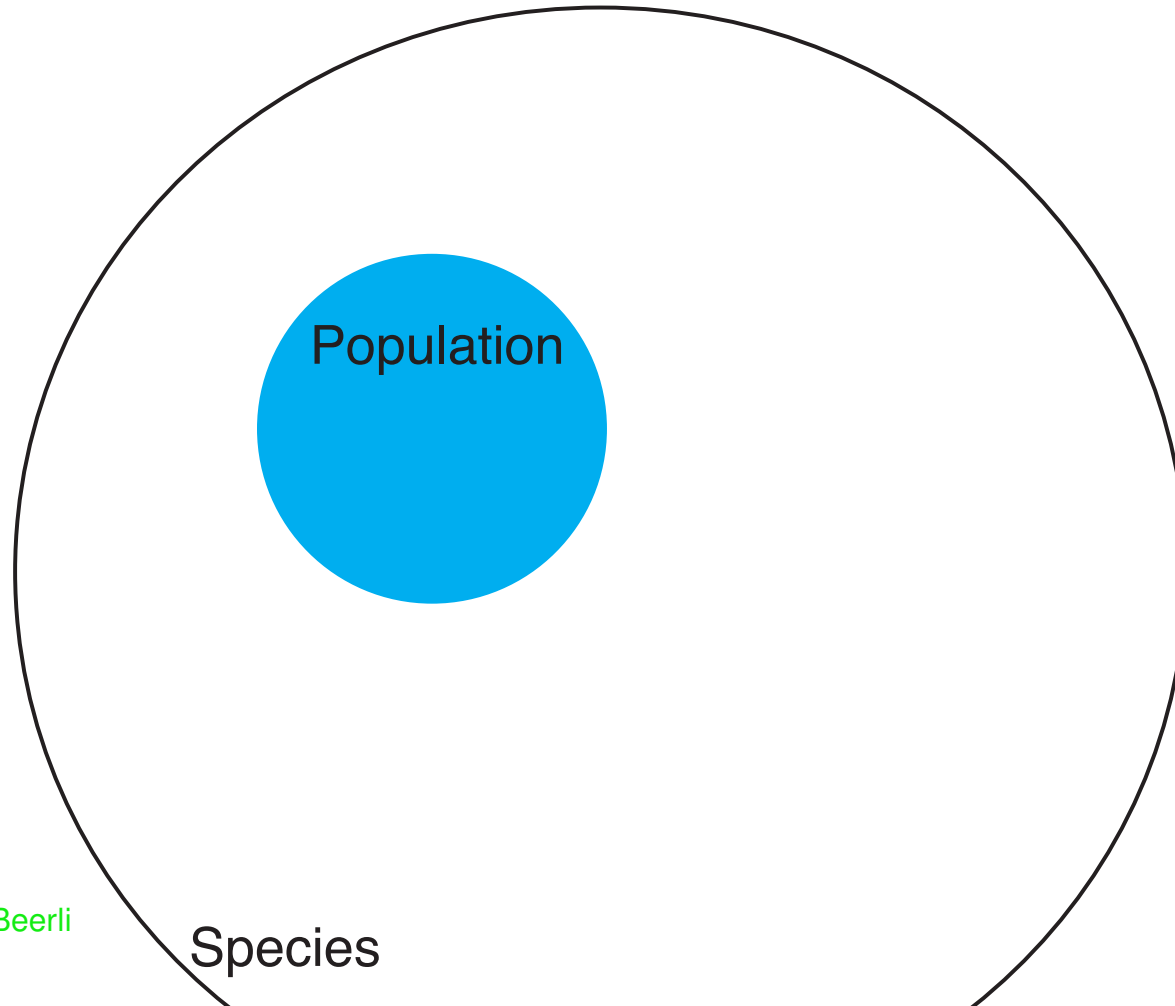


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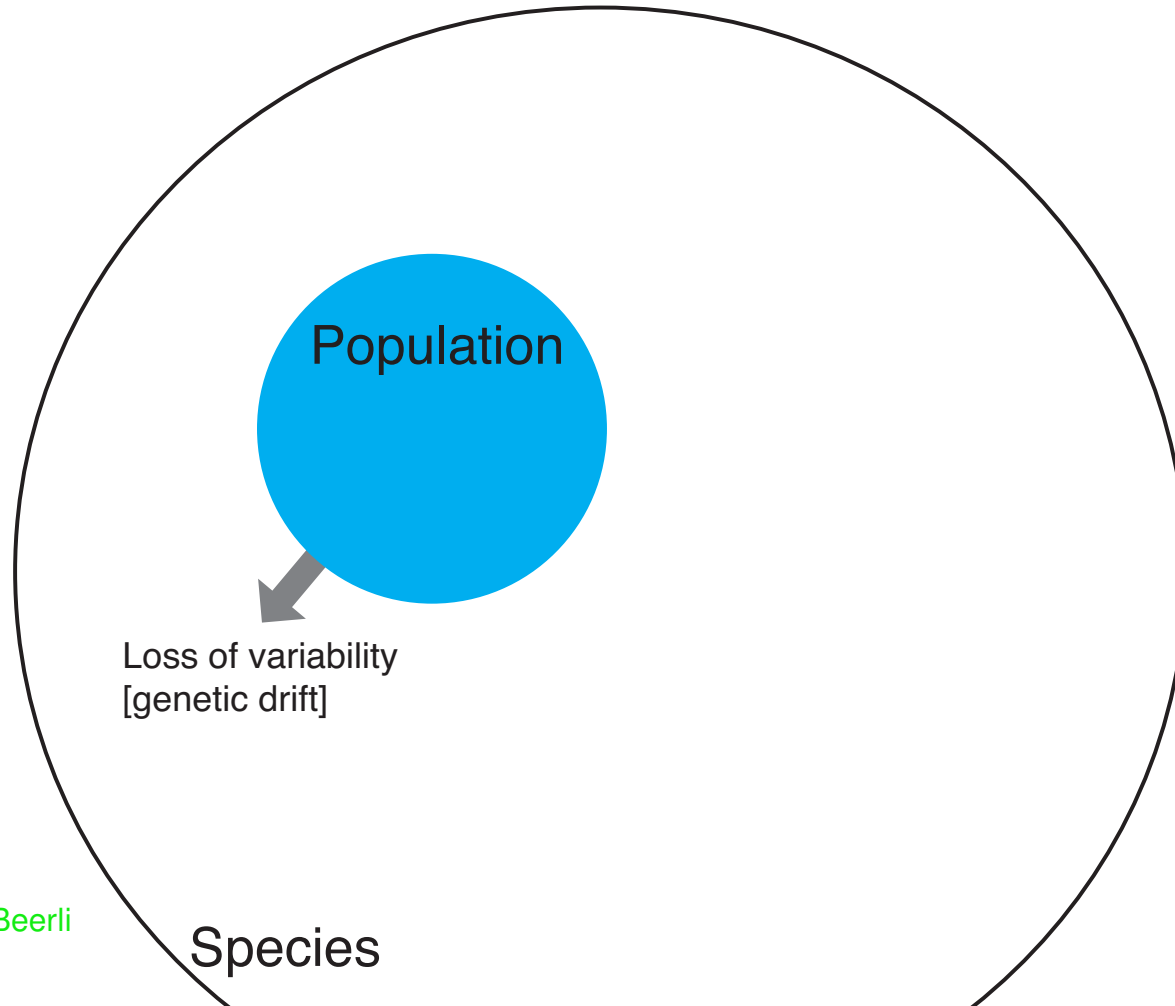
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Species

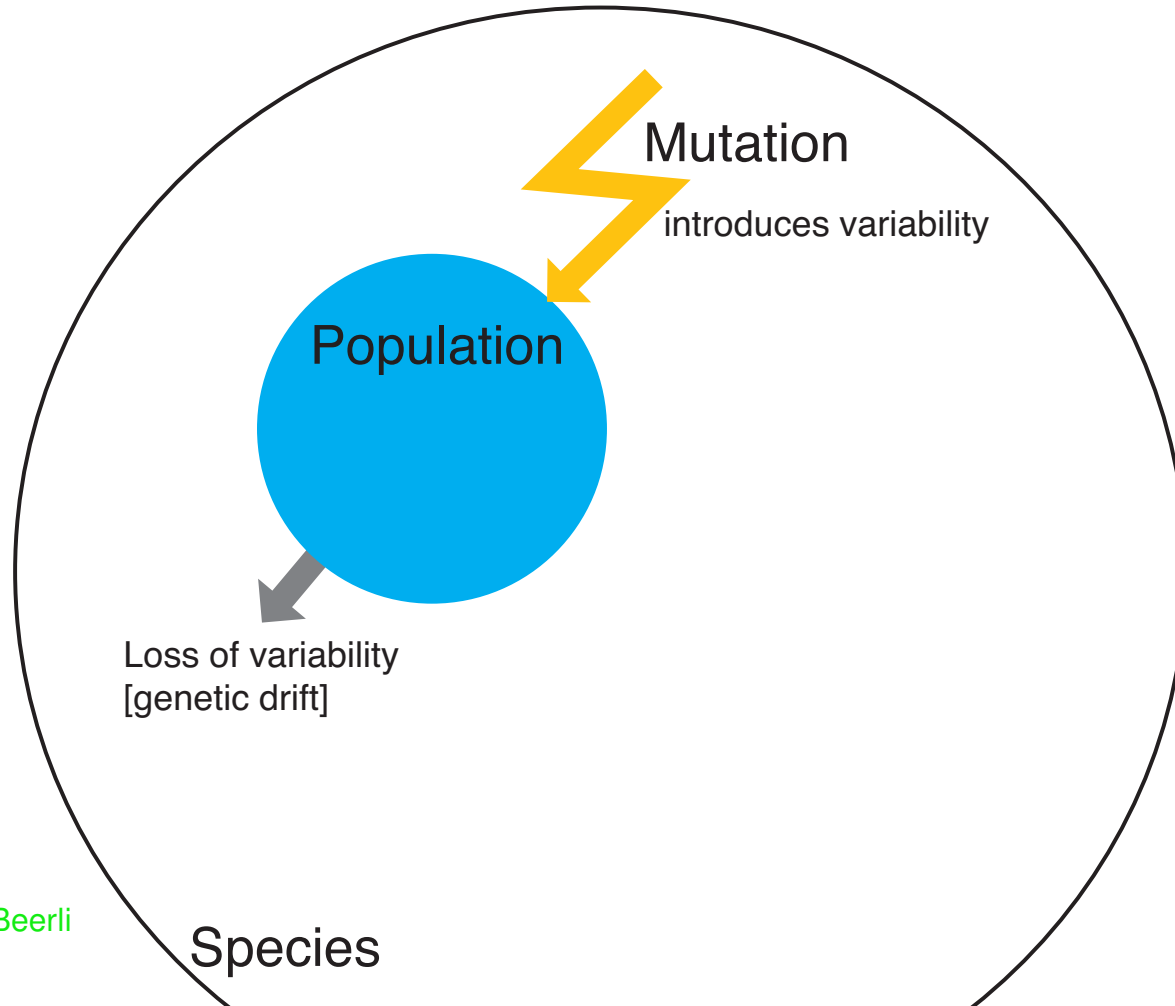
Population models



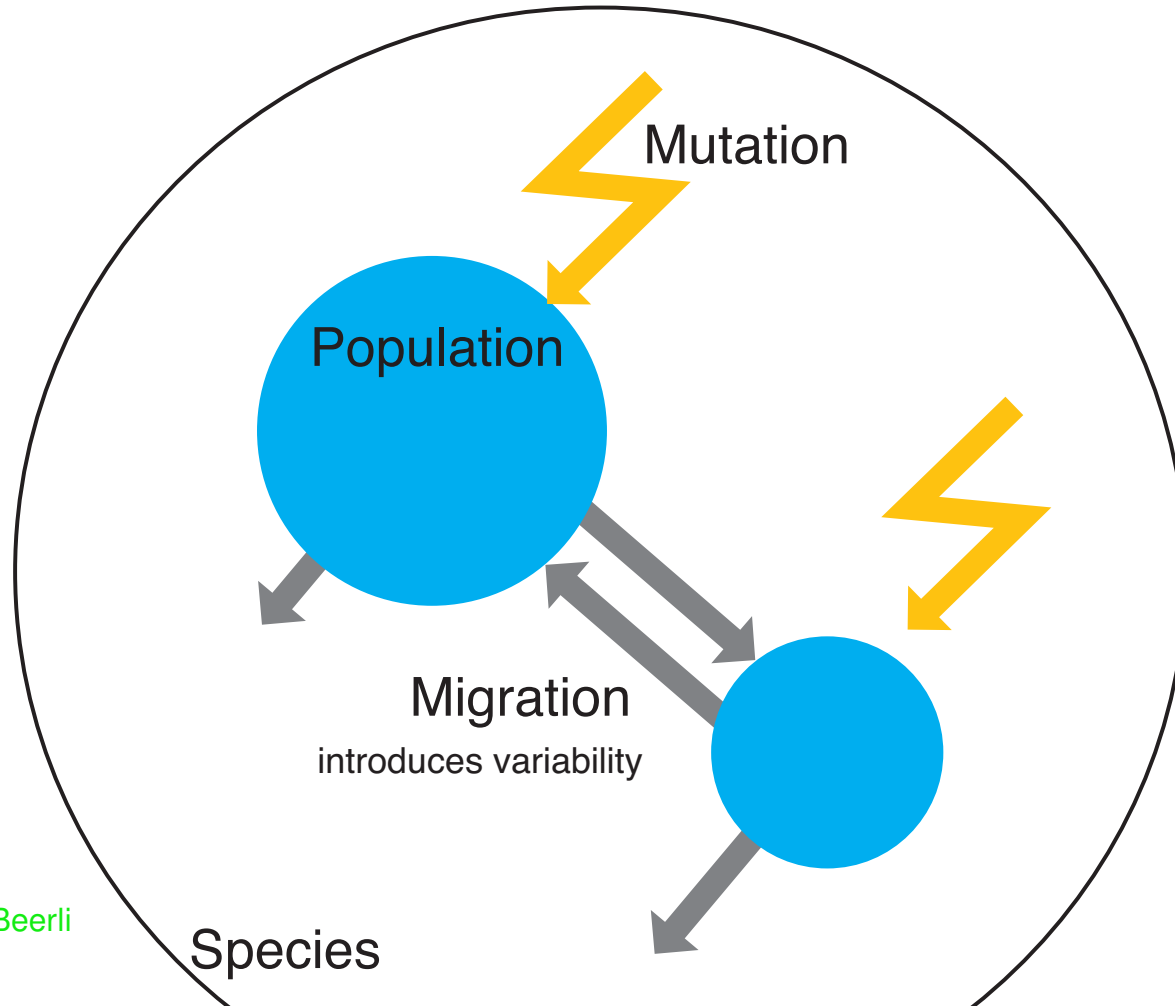
Population models



Population models



Population models



Population models

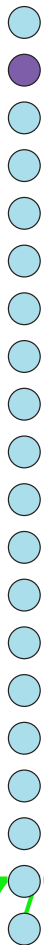
Population size = $f(\text{Alleles, Mutation, Migration, population size in last generation})$

$$N_t = f(X, \mu, m, N_{t-1})$$

Simply looking only at a single population this is

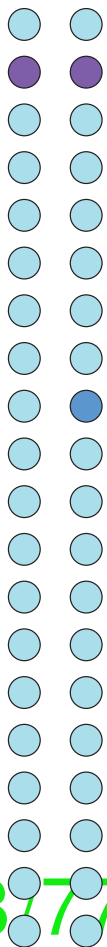
$$N_t = f(X, \mu, N_{t-1})$$

Population models

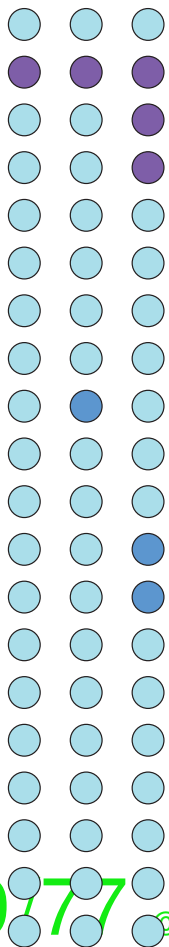


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Population models

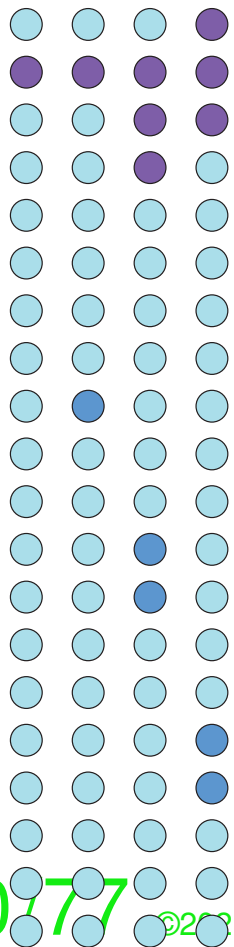


Population models



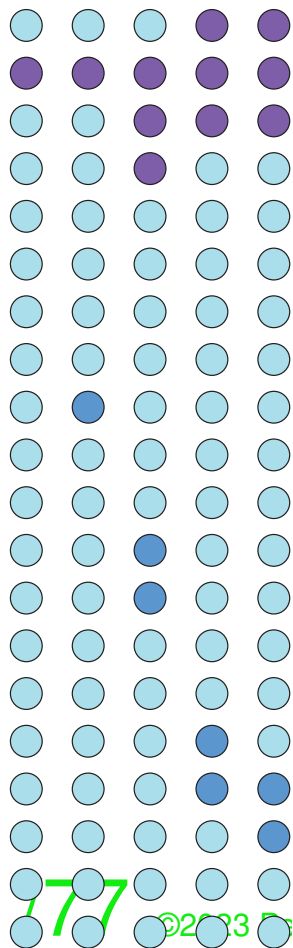
1977 €

Population models



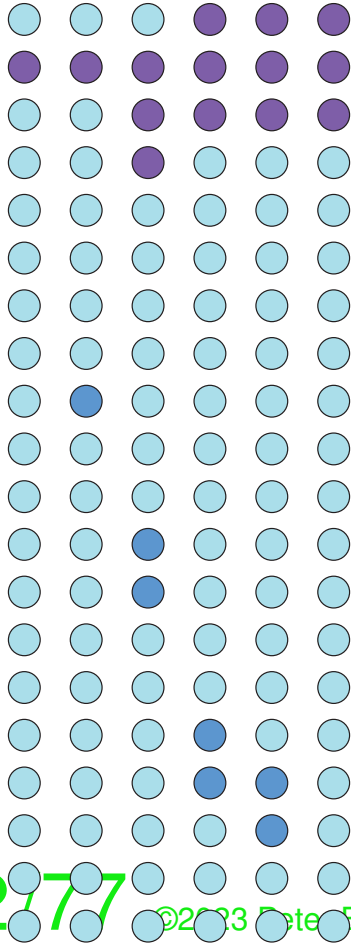
20177 2017

Population models

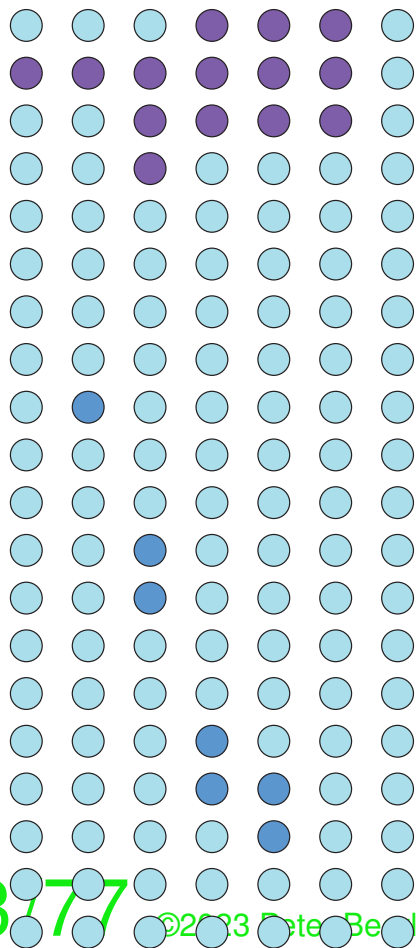


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©2023 D

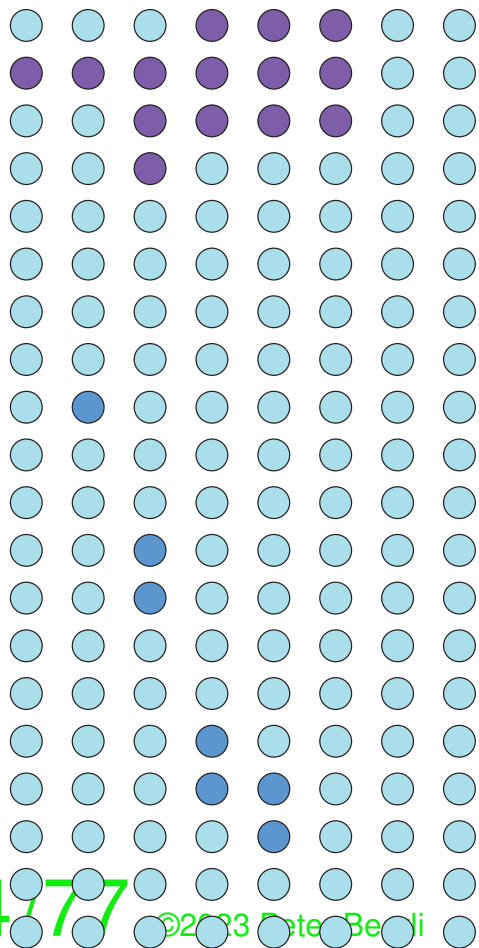
Population models



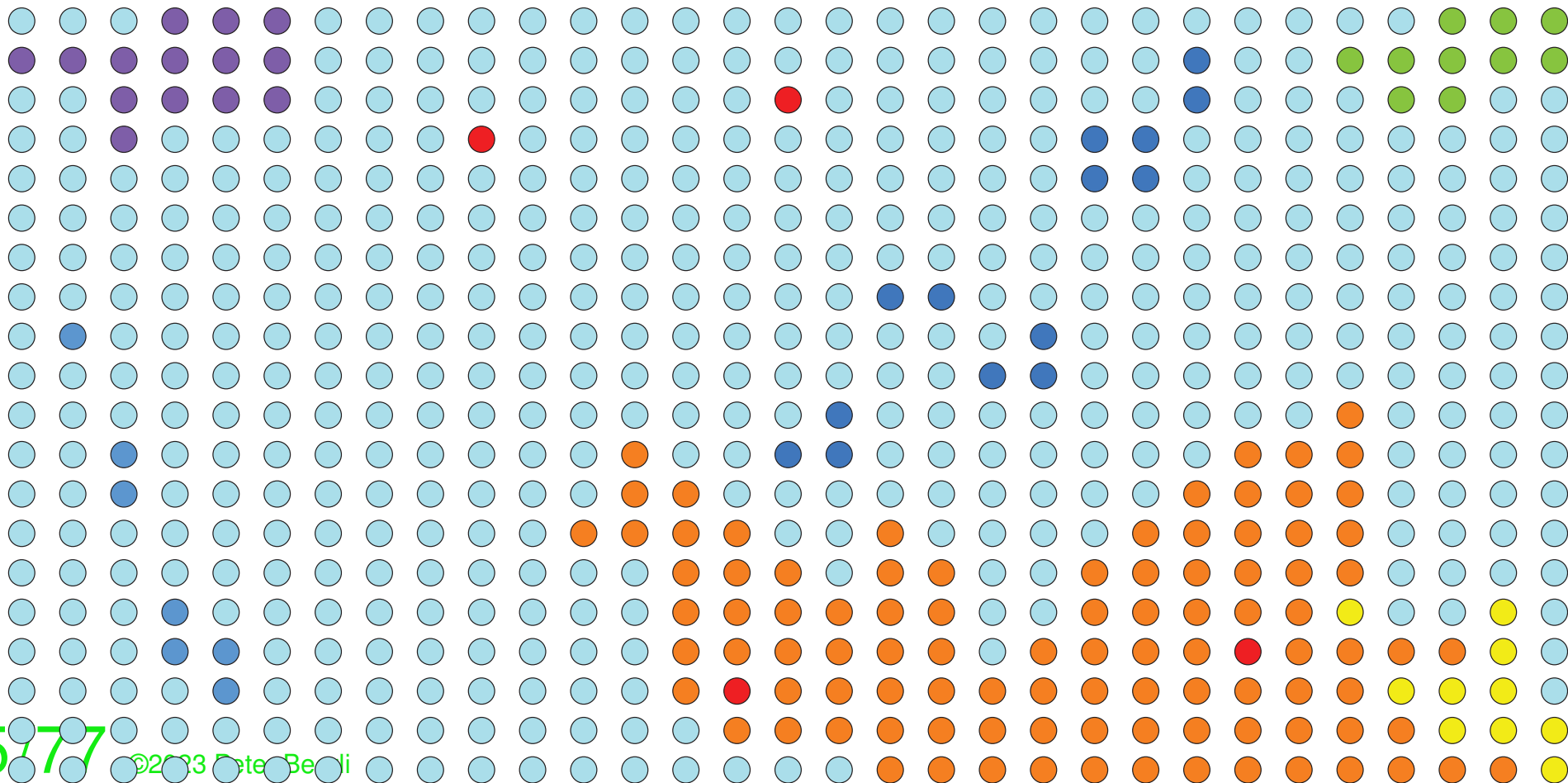
Population models



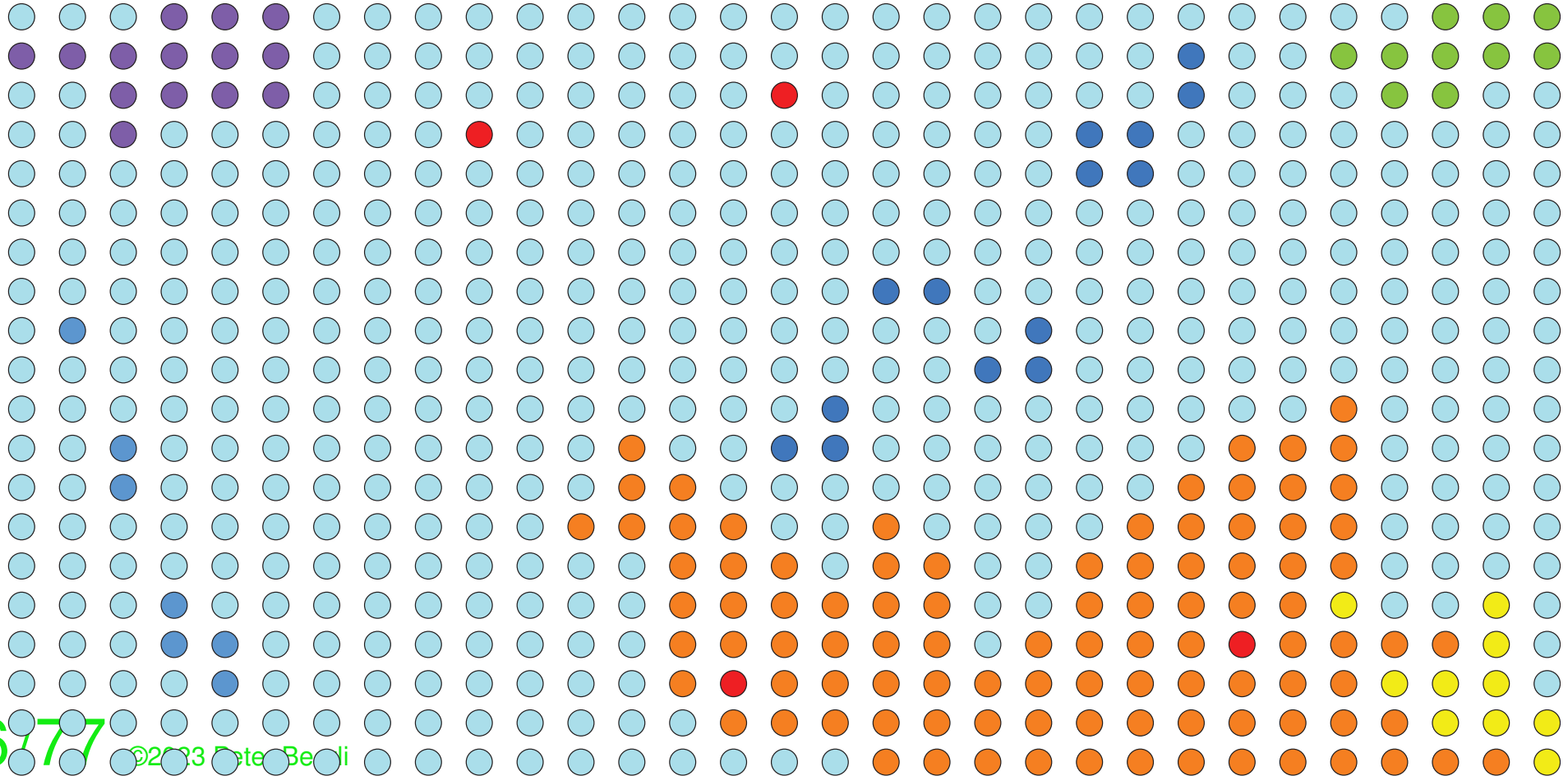
Population models



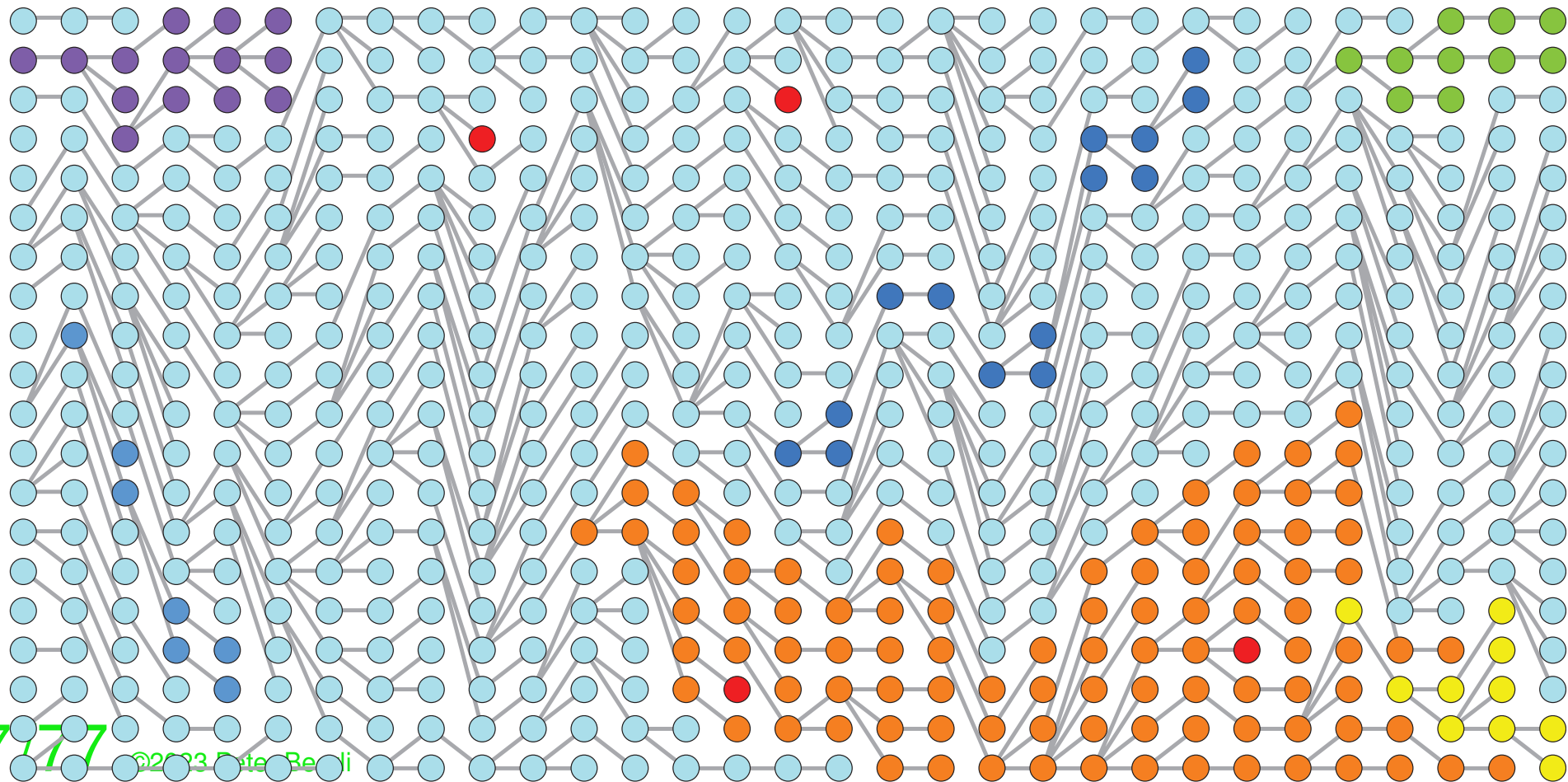
Population models



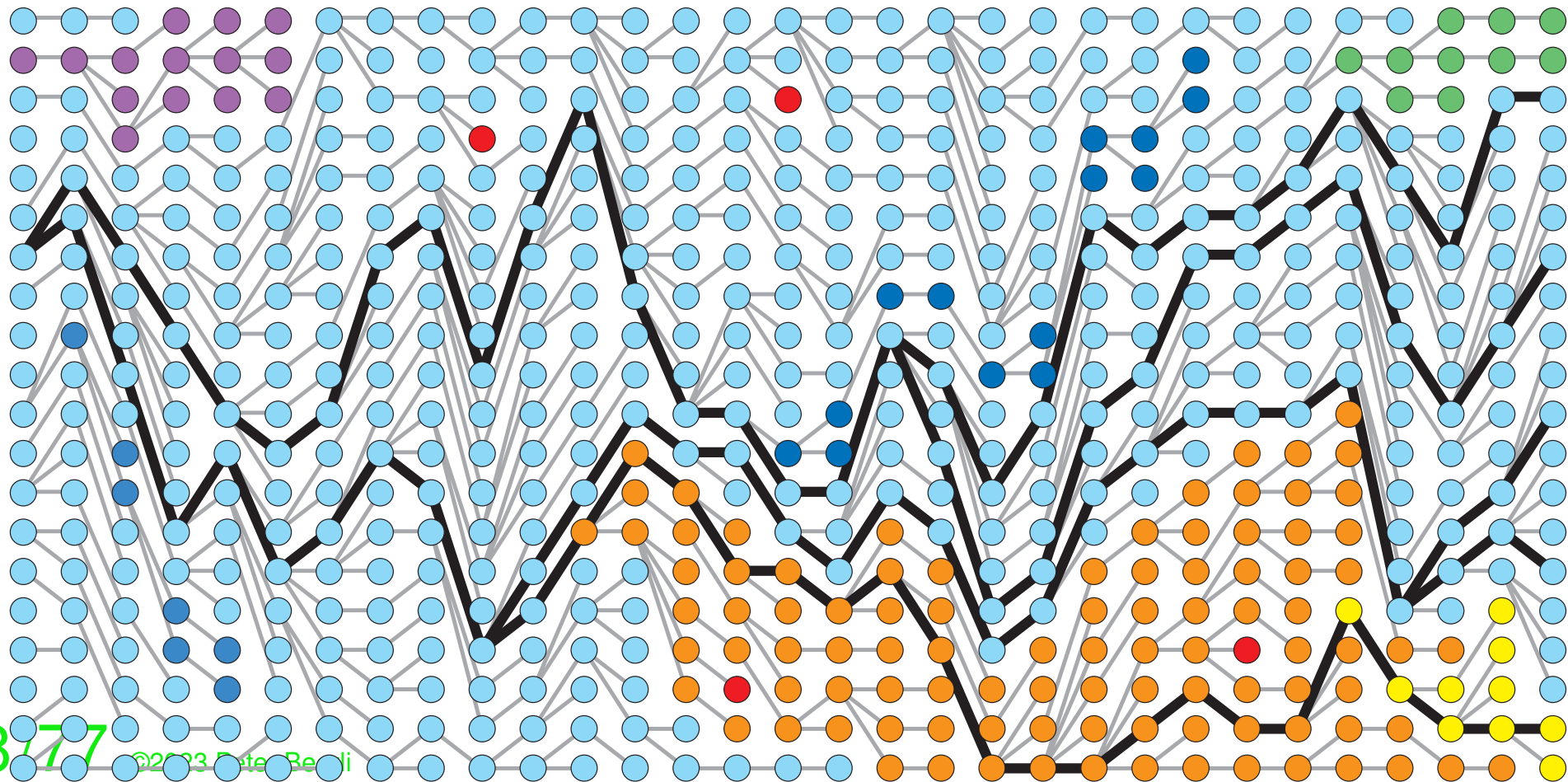
Population models



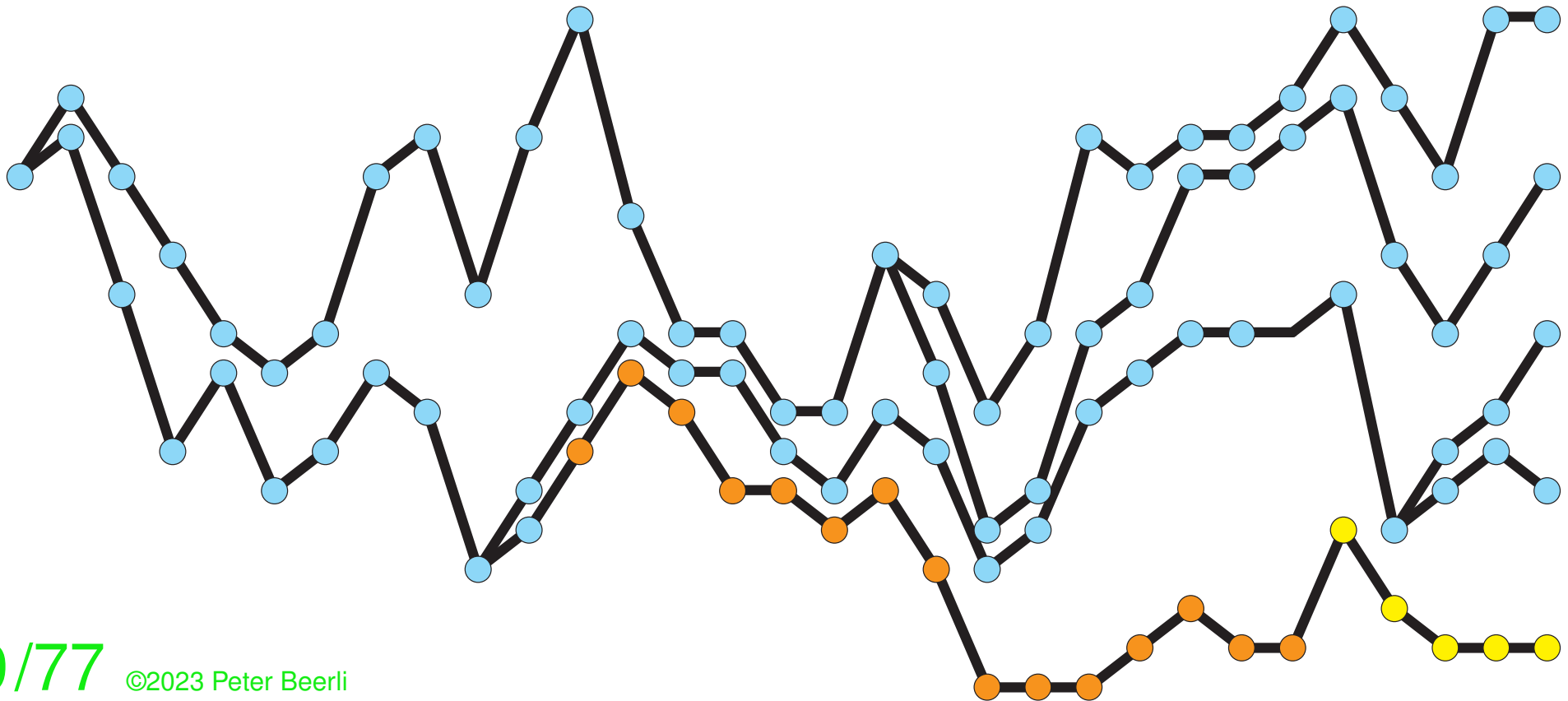
Population models



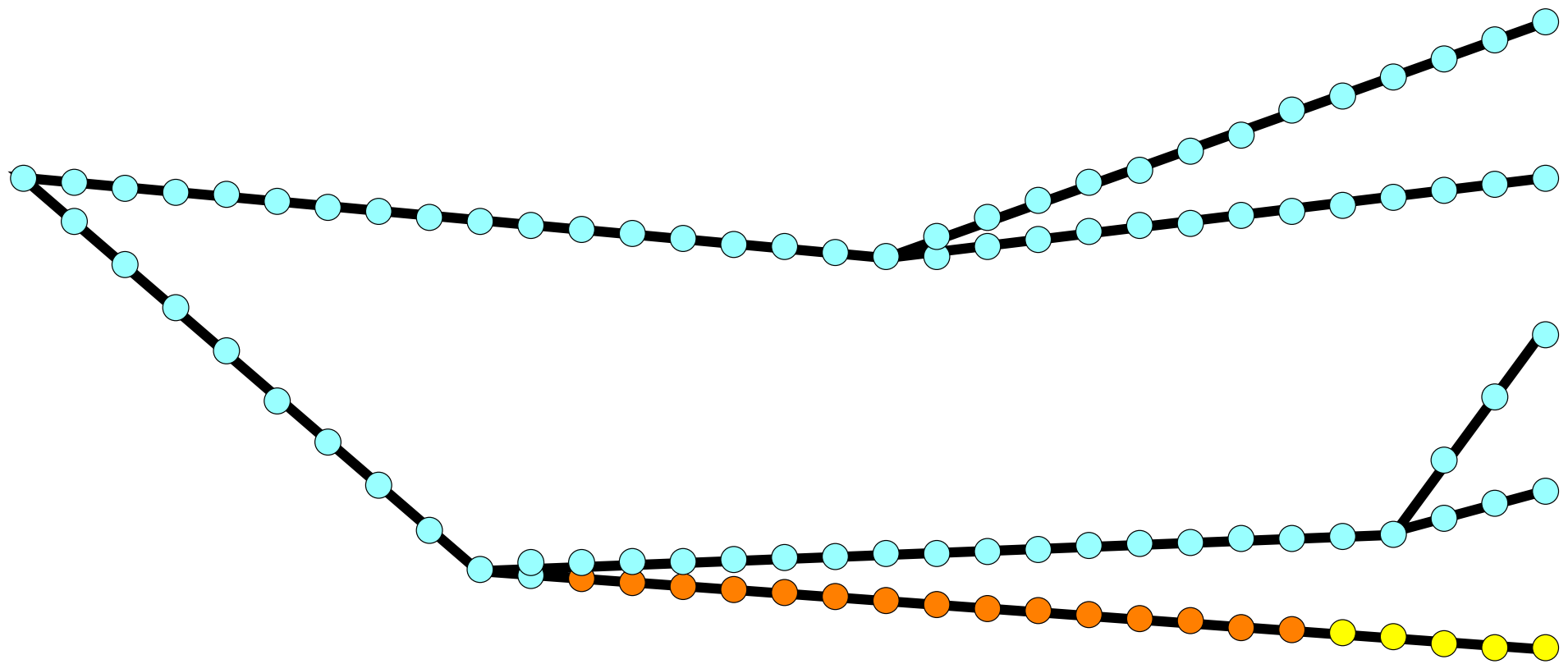
Population models



Population models



Population models

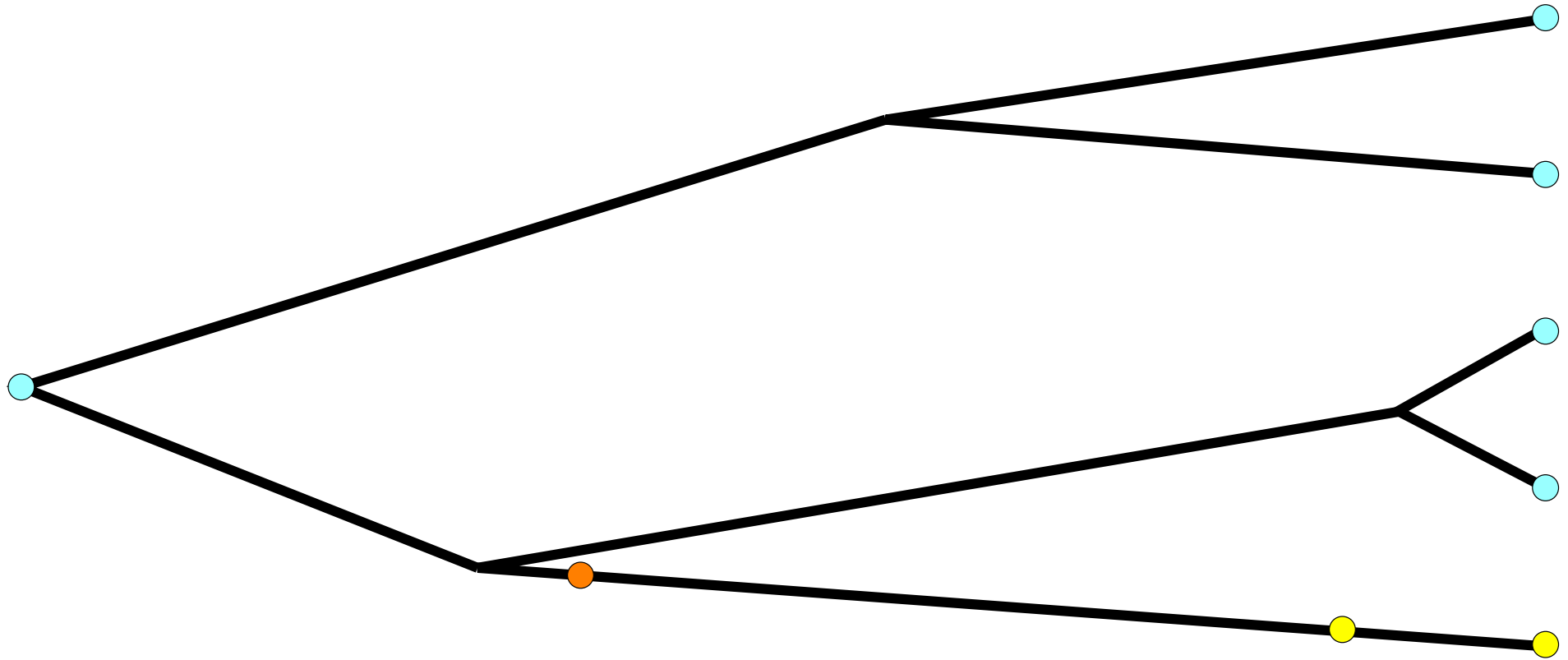


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past

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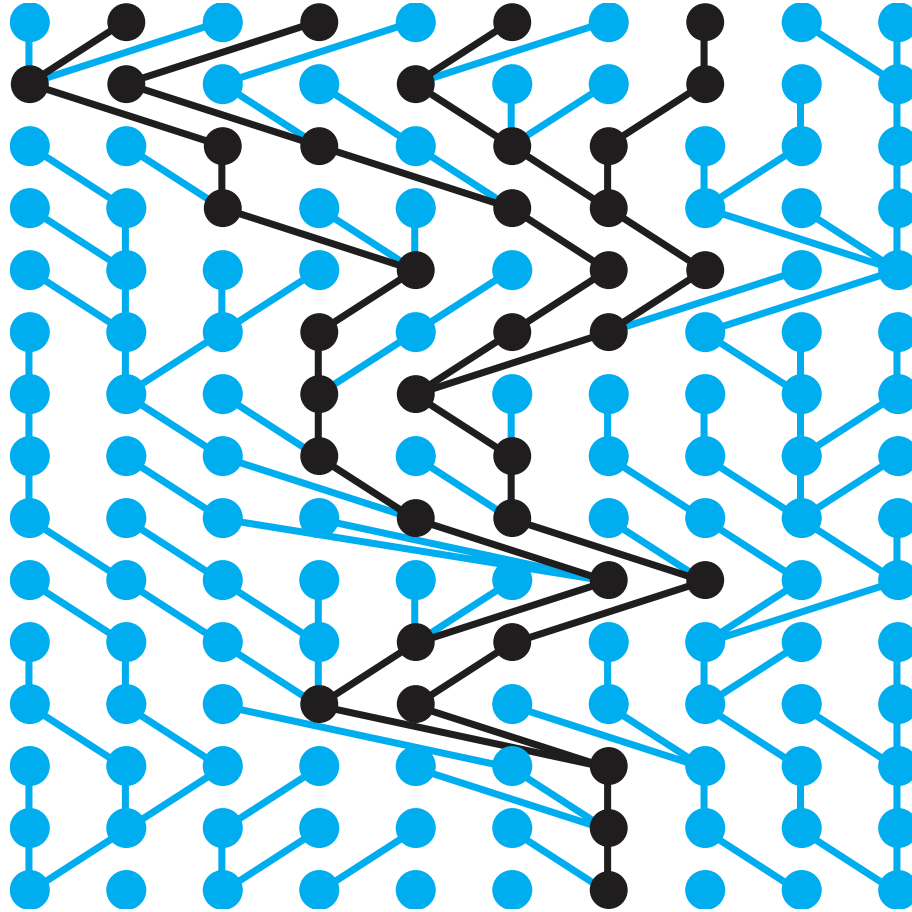
present

Population models



Coalescence theory

Present



Past

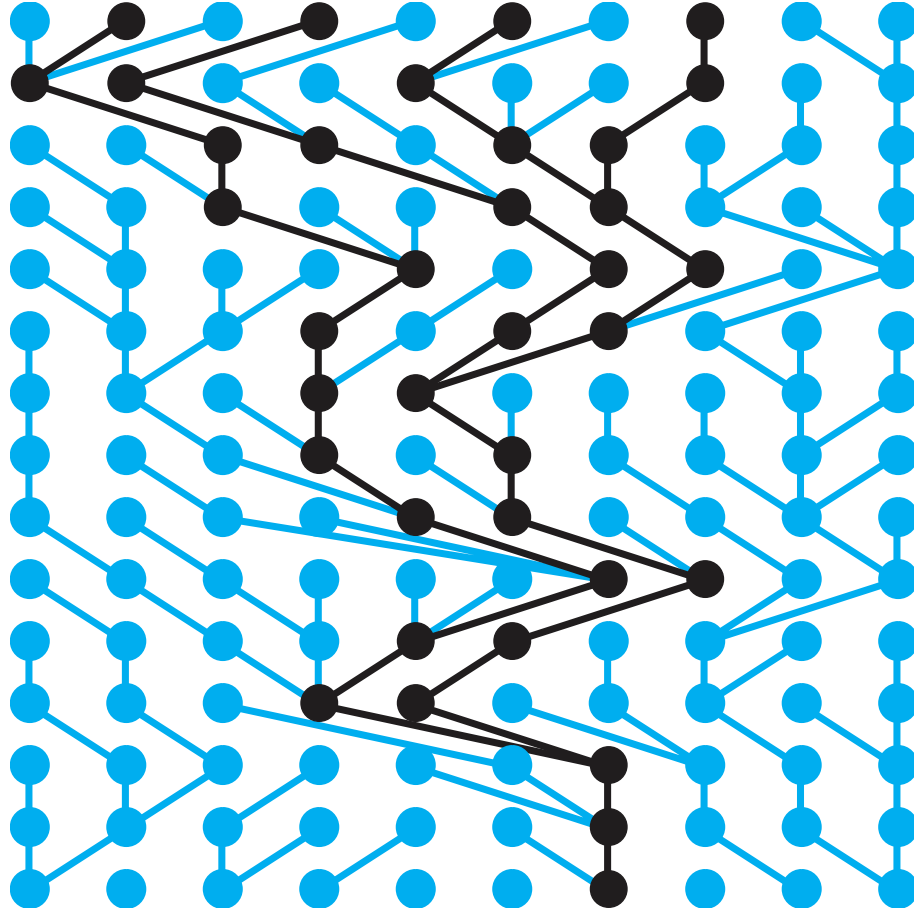
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Coalescence theory

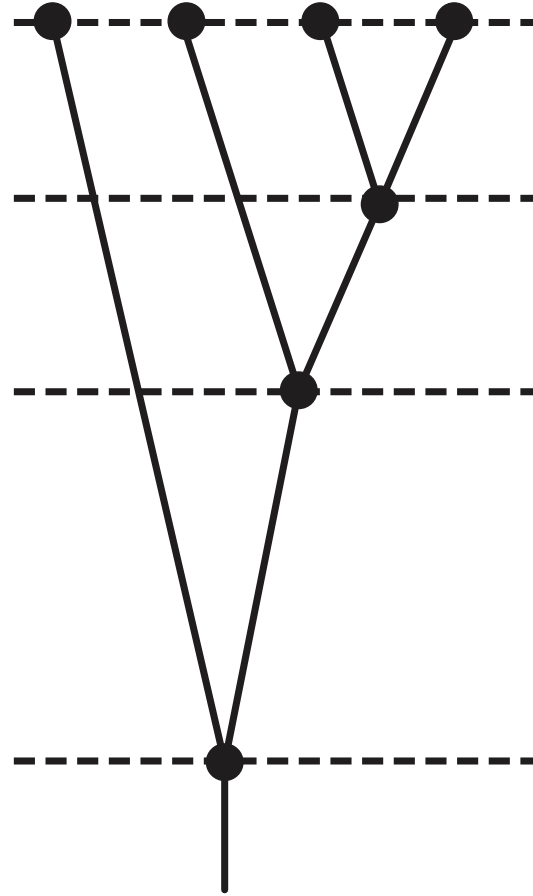
Present



Past

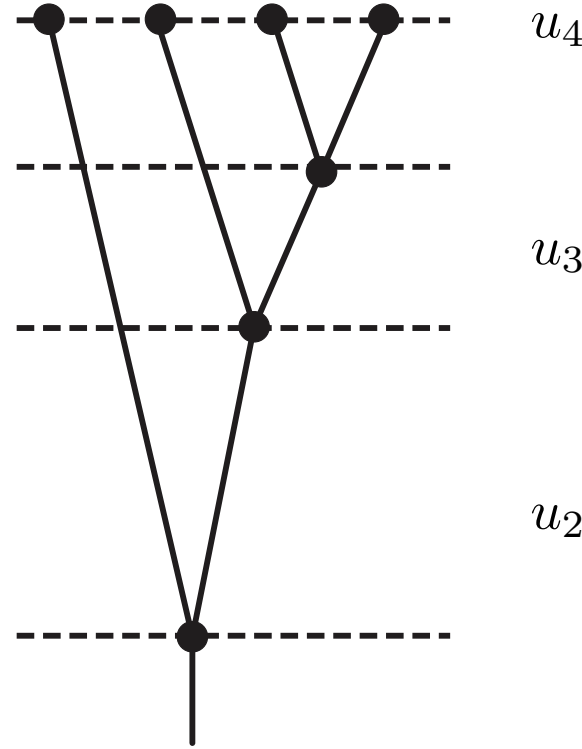
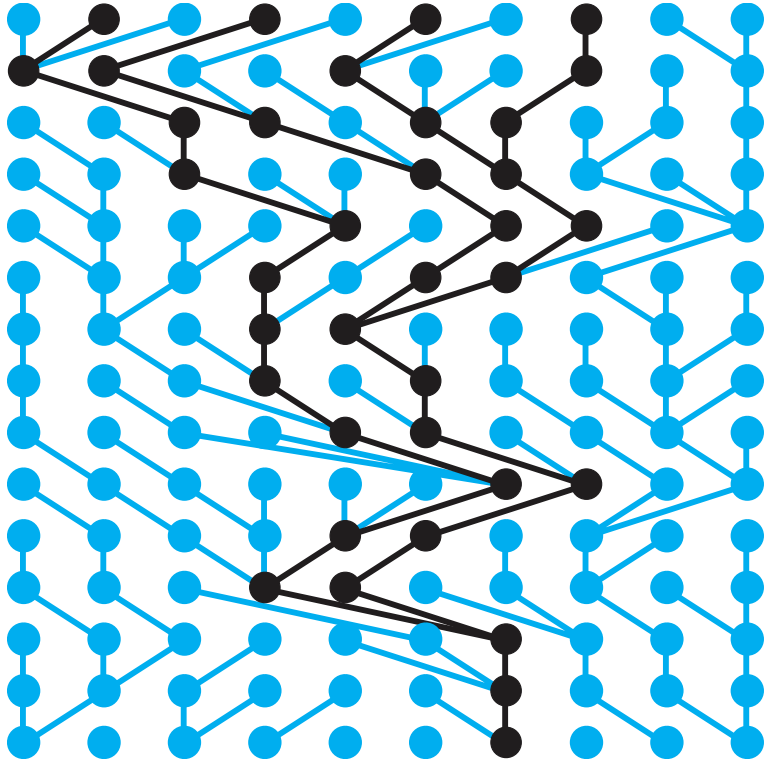
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Coalescence theory

Present



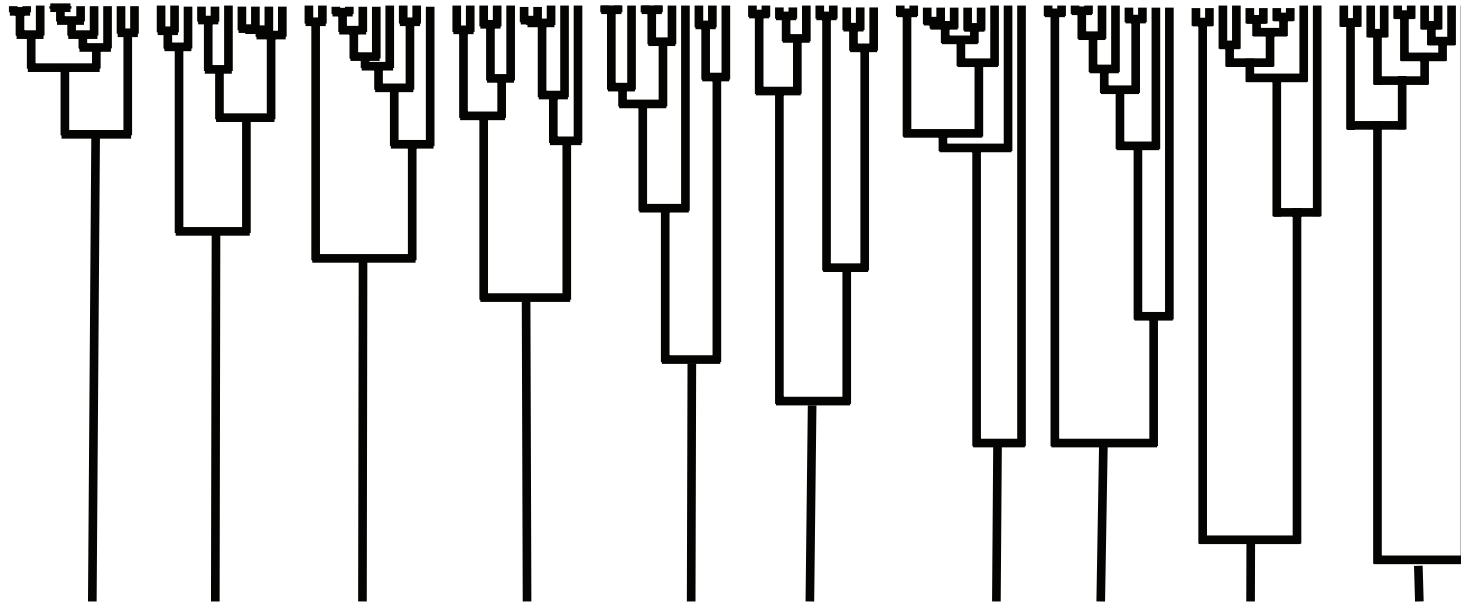
Past

The time intervals u_k follows an exponential distribution with

$$\mathbb{E}(u_k) = \frac{\Theta}{k(k-1)}$$

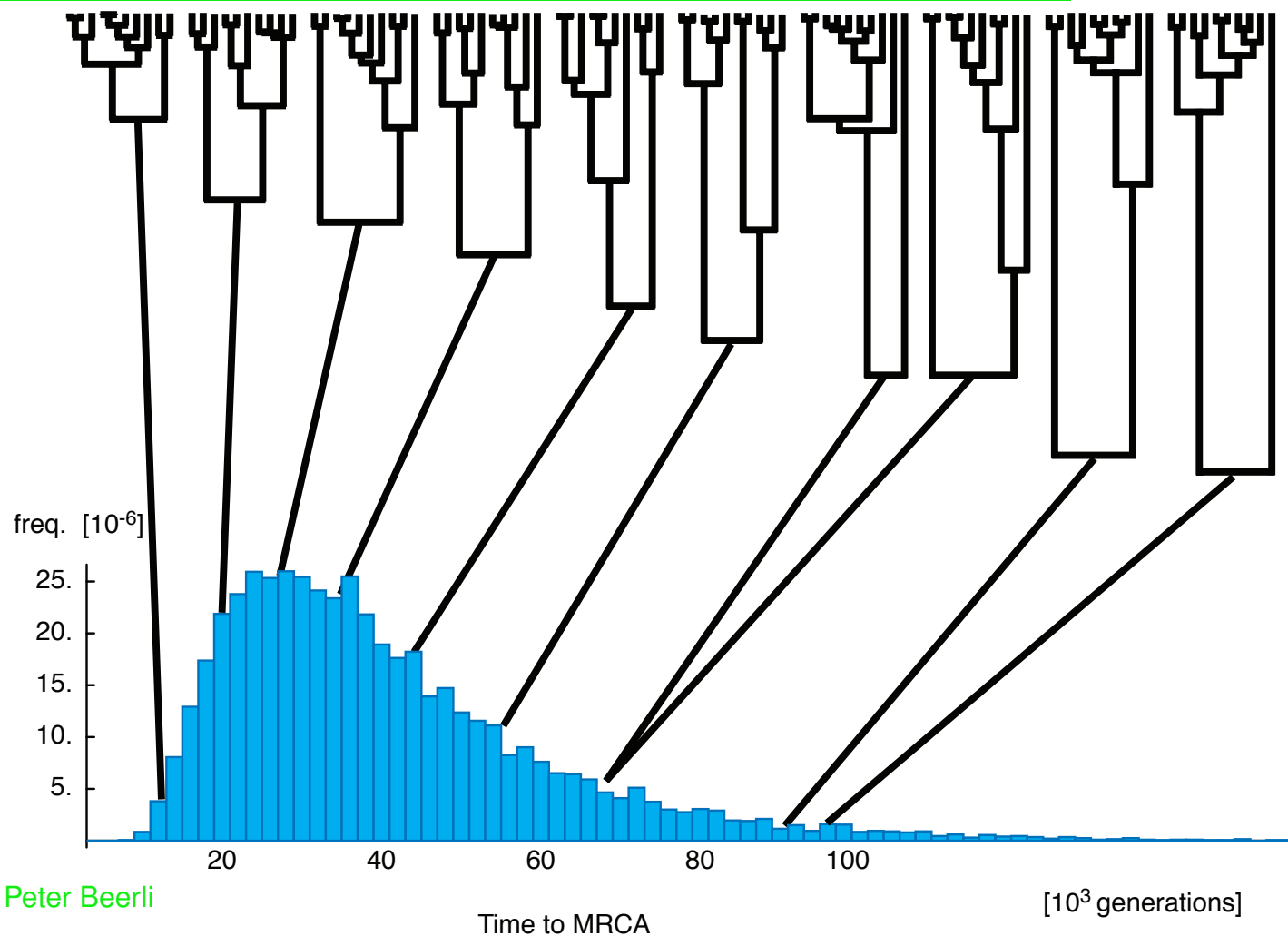
$$p(G \mid \Theta, n) = \prod_{k=2}^n \exp(-u_k \frac{k(k-1)}{\Theta}) \frac{2}{\Theta}$$

Variability of the coalescent process



All genealogies were simulated with the same population size $N_e = 10,000$

Variability of the coalescent process



Population Parameter Inference


$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Population Parameter Inference

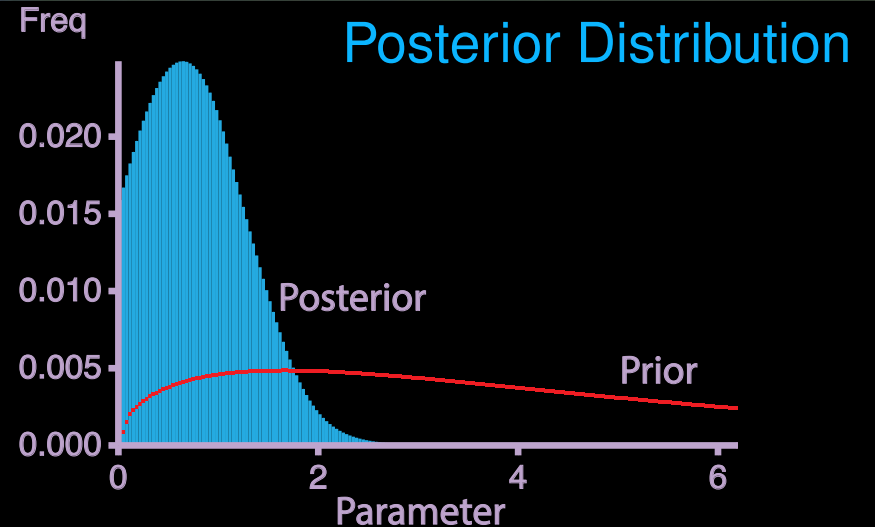
$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Genetic Data 

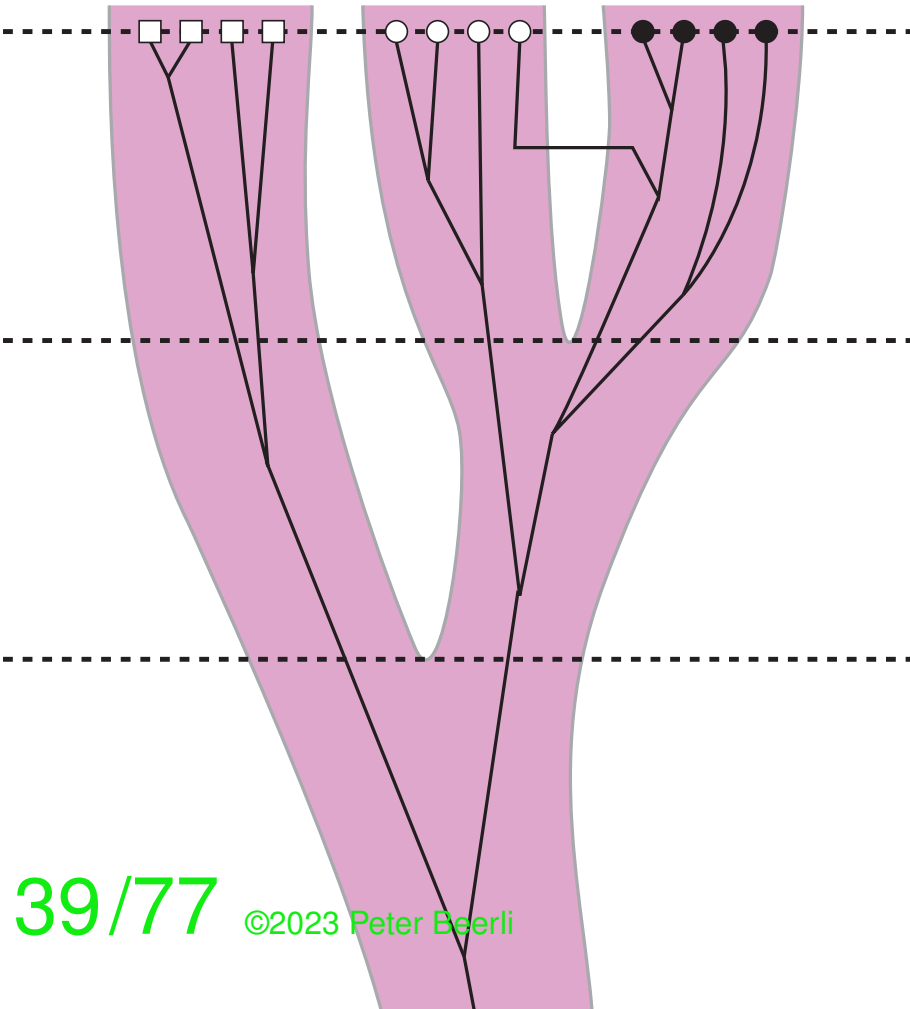
Mutation model 

Population model 

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Population model



The relationship among individuals can be expressed, looking backward in time, by a waiting process where random lineages

- ◆ coalesce
- ◆ migrate between populations
- ◆ split off an ancestral population

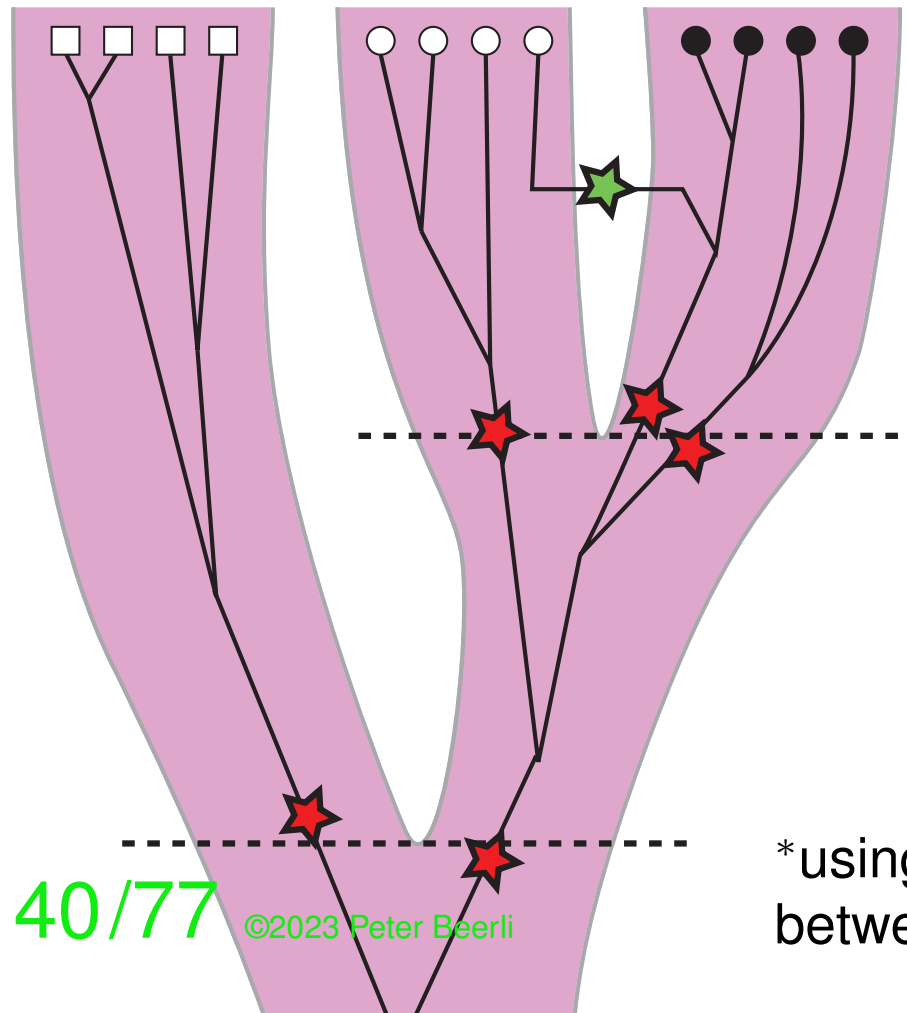
Population genetics

Each of these processes can be expressed as a waiting time process with rate λ for N populations and k_j lineages in population j :

$$\lambda_{\text{two lineages coalesce}} = \sum_{j=1}^N \frac{k_j(k_j - 1)}{4N}$$

$$\lambda_{\text{lineages migrate}} = \sum_{j=1}^N \sum_{i=1, i \neq j}^N k_j m_{ij}$$

$$\lambda_{\text{lineages split off}^*} = \frac{k \sqrt{\frac{2}{\pi}} e^{-\frac{(t-\mu)^2}{2\sigma^2}}}{\sigma \left(1 - \operatorname{erf} \left(\frac{t-\mu}{\sqrt{2}\sigma} \right) \right)}$$



*using a Normal distribution to model the splitting time between two populations.

Combining the parts

$$P(\Theta | \mathbf{D}_1, \mathbf{D}_2, \dots, \mu) = \frac{P(\Theta) P(\mathbf{D}_1, \mathbf{D}_2, \dots | \Theta)}{P(\mathbf{D}_1, \mathbf{D}_2, \dots)} = \frac{P(\Theta) \int_G P(G | \Theta) \prod_i^{n_{\text{Loci}}} P(\mathbf{D}_i | G, \mu) dG}{\int_{\Theta} P(\Theta) \int_G P(G | \Theta) \prod_i^{n_{\text{Loci}}} P(\mathbf{D}_i | G, \mu) dG d\Theta}$$

$$P(G | \Theta) = \prod_{i=1}^K \lambda_x \exp(-t_i [\lambda_{\text{coalescence}} + \lambda_{\text{migration}} + \lambda_{\text{splitting}}])$$

Θ

vector of parameters for population size, migration and splitting parameters.

$\mathbf{D}_1, \mathbf{D}_2, \dots$

independent genetic sequence data,

μ

mutation model,

G

nuisance genealogies that we integrate out (we are interested in the parameters not the trees).

x

the particular event on the genealogy

K

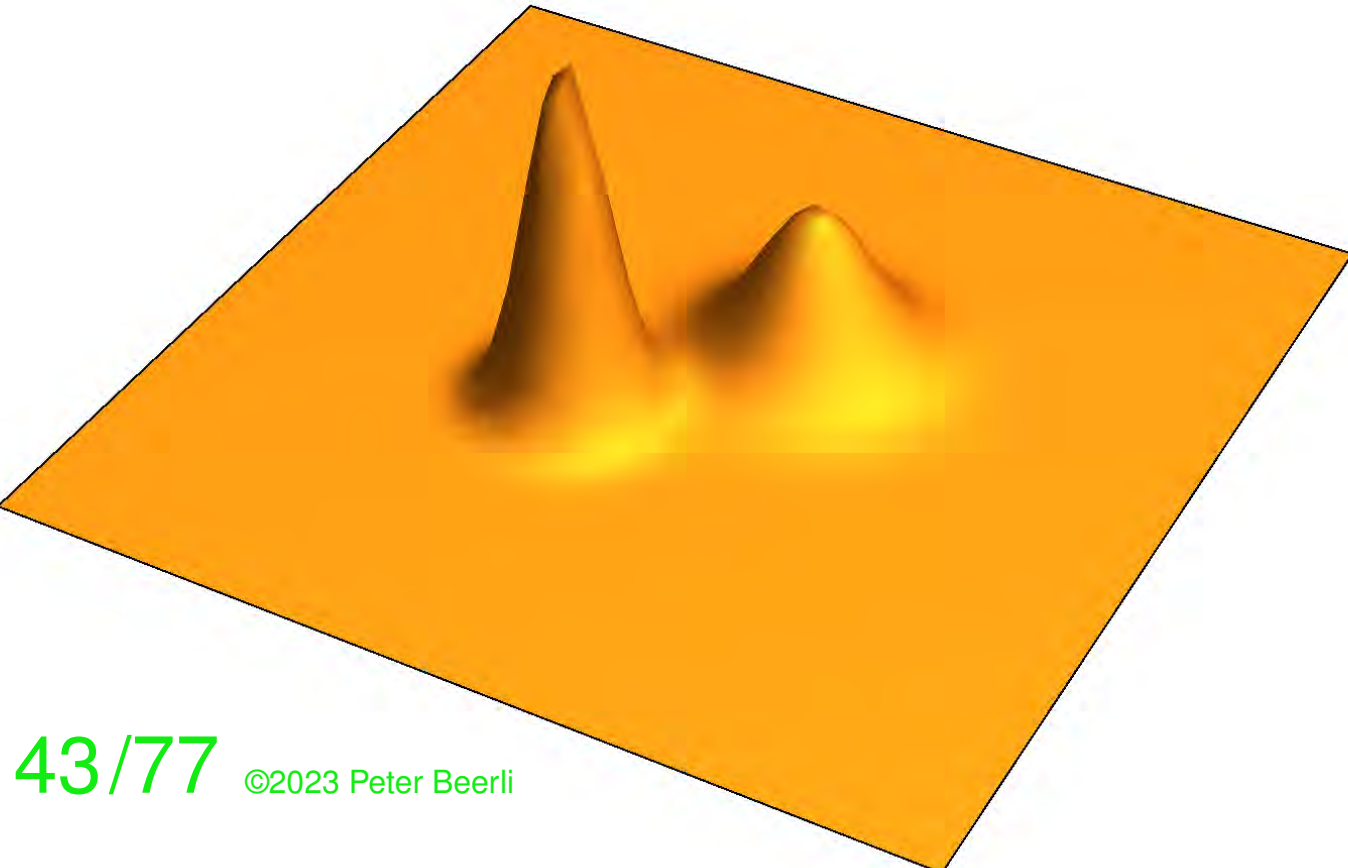
number of total events on the genealogy

Finally....

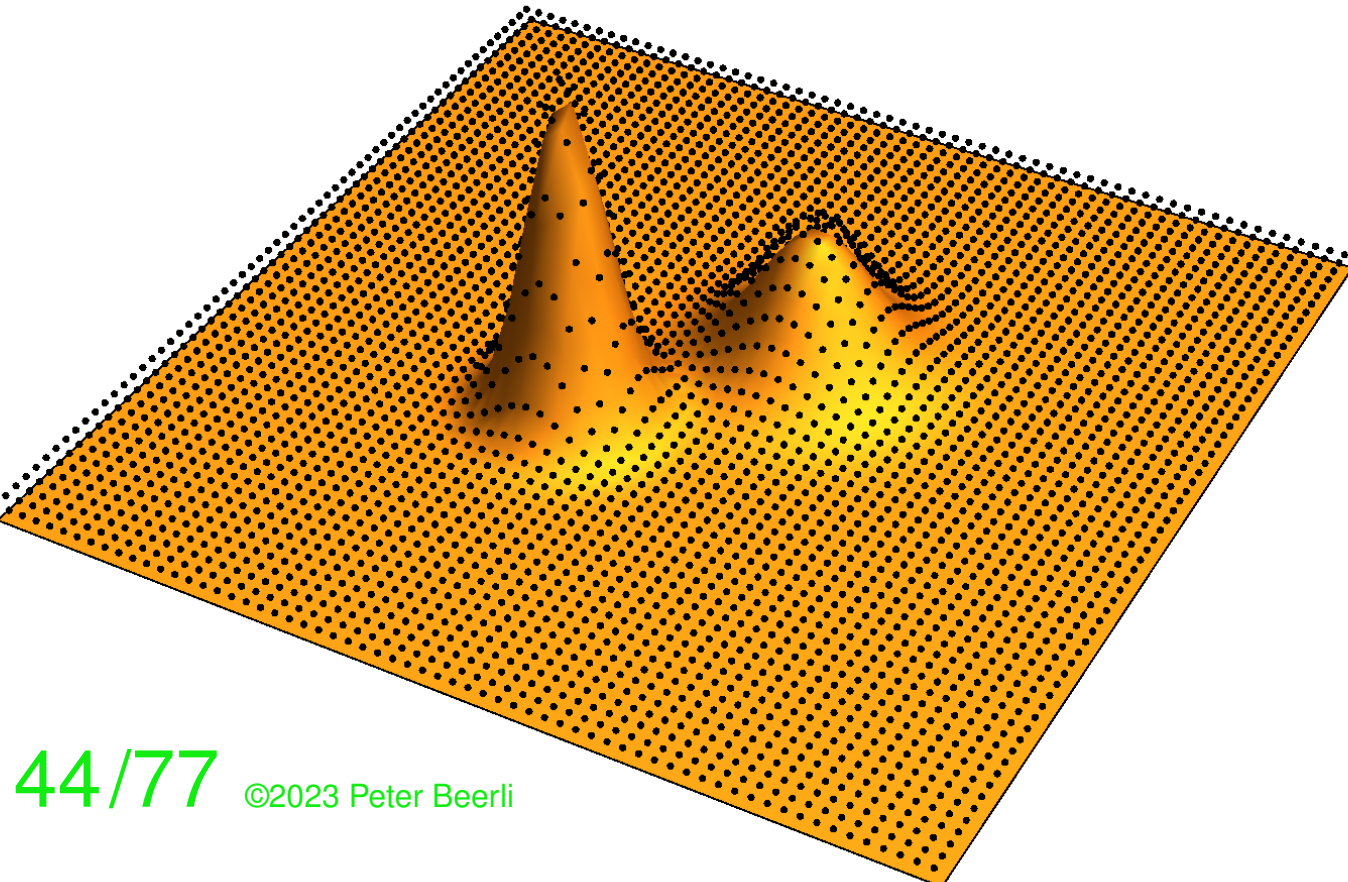
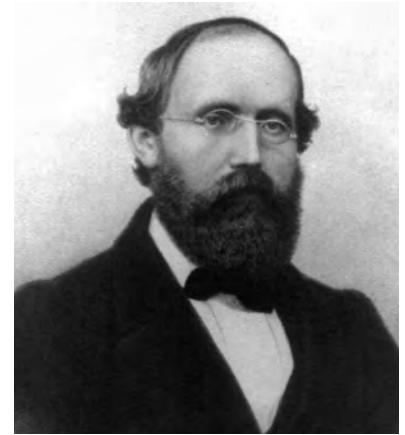
$$p(D|\Theta) = \int_G p(G|\Theta)p(D|G)dG$$

The number of possible genealogies is very large and for realistic data sets, programs need to use Markov chain Monte Carlo methods.

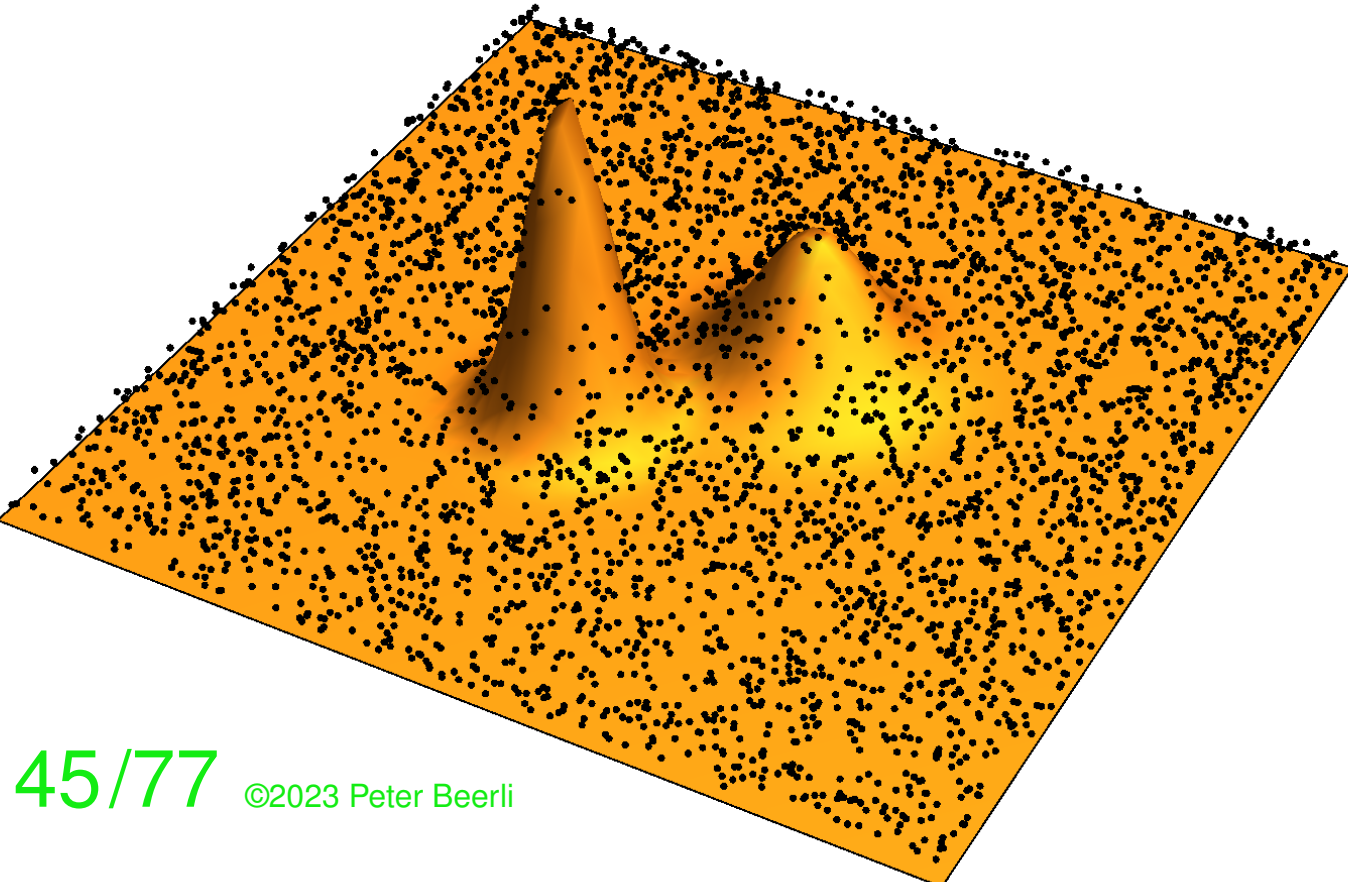
Naive integration approach



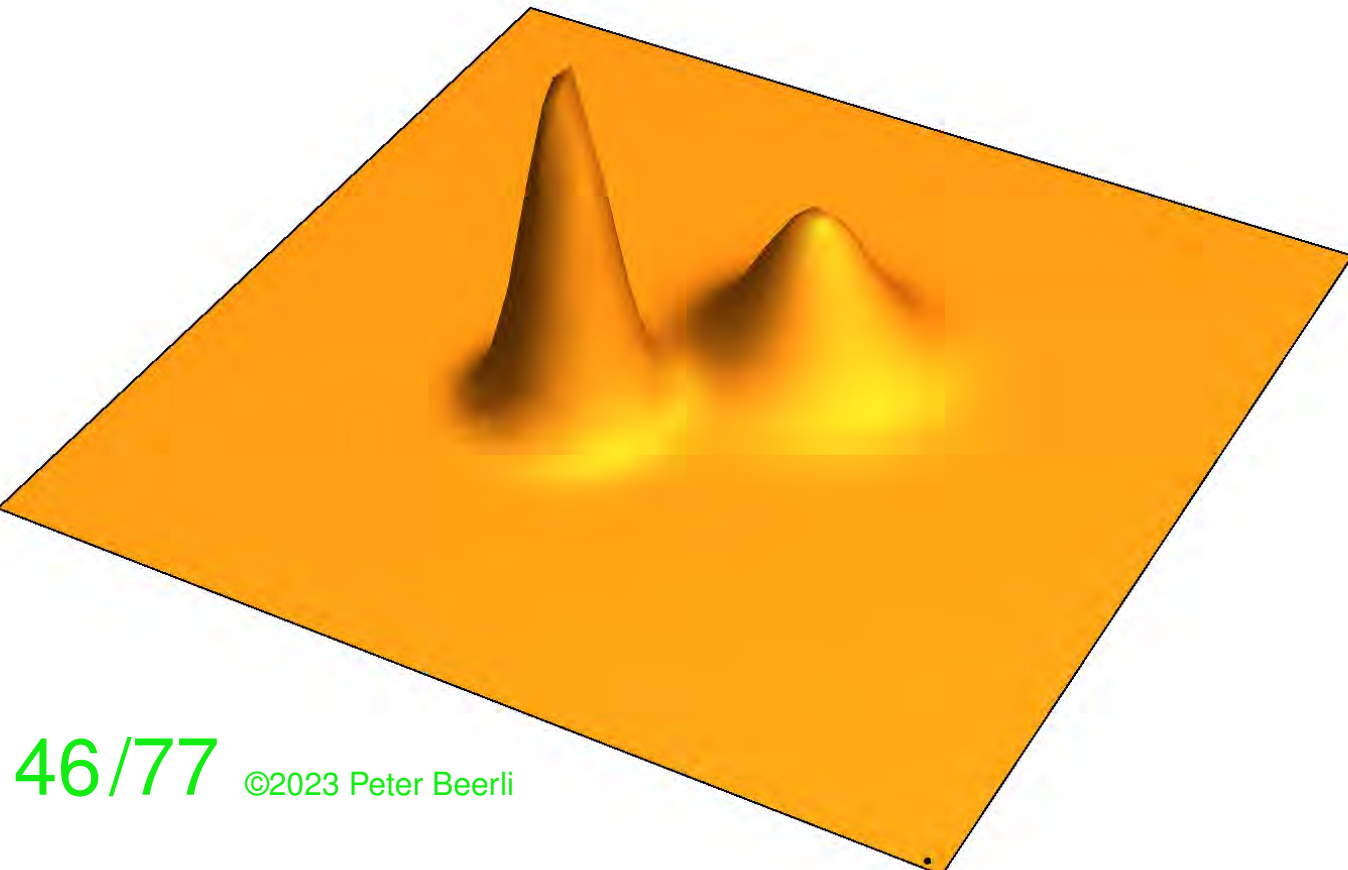
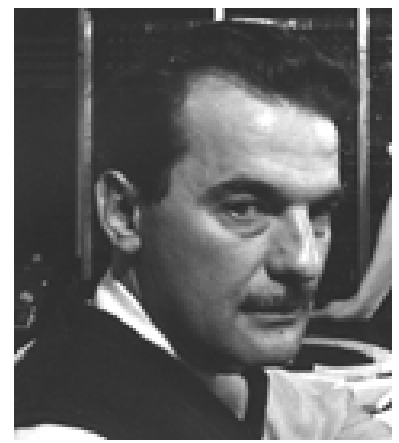
Naive integration approach



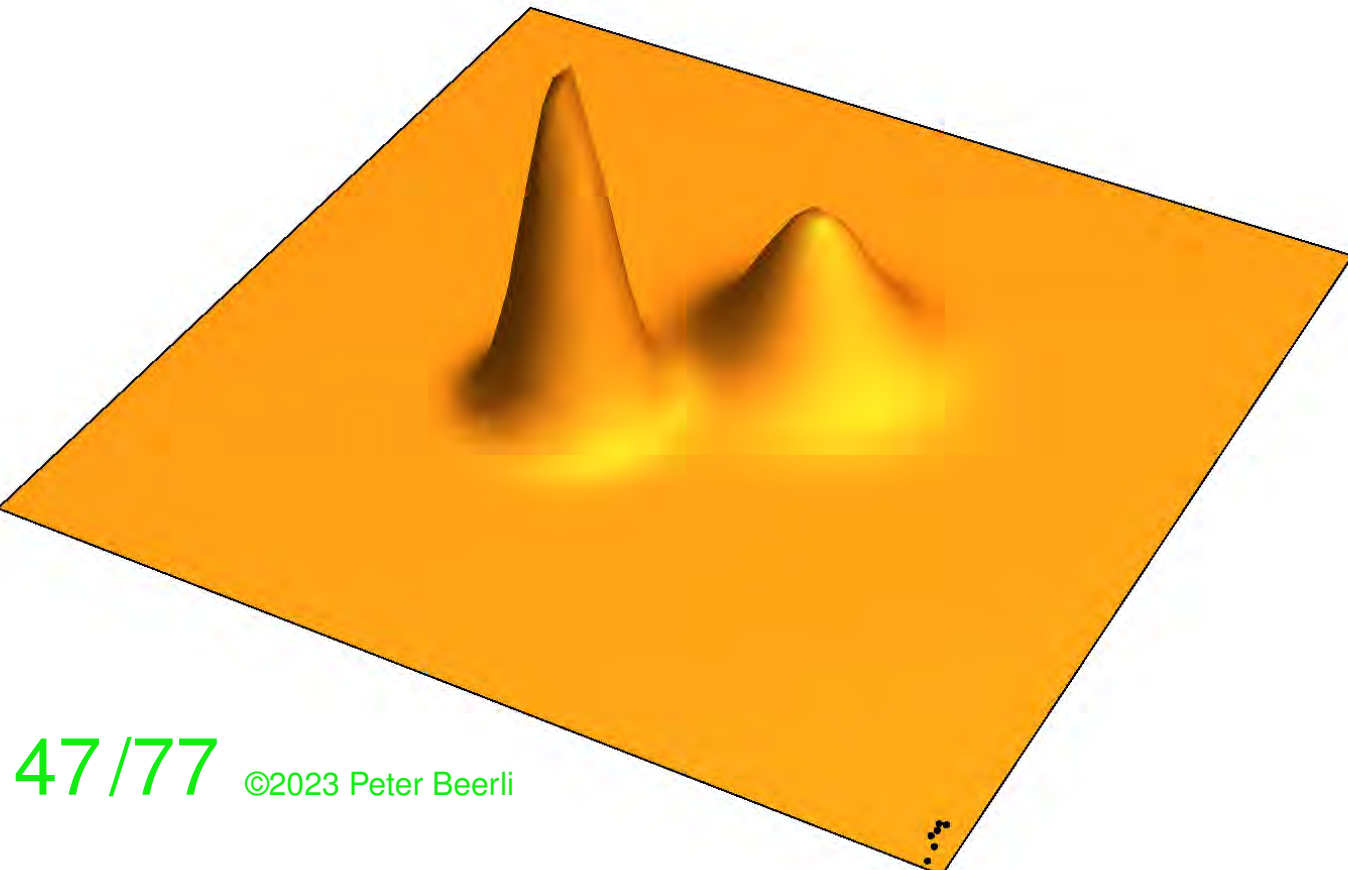
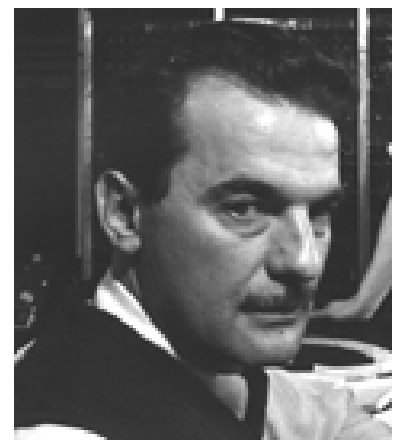
Another naive integration approach



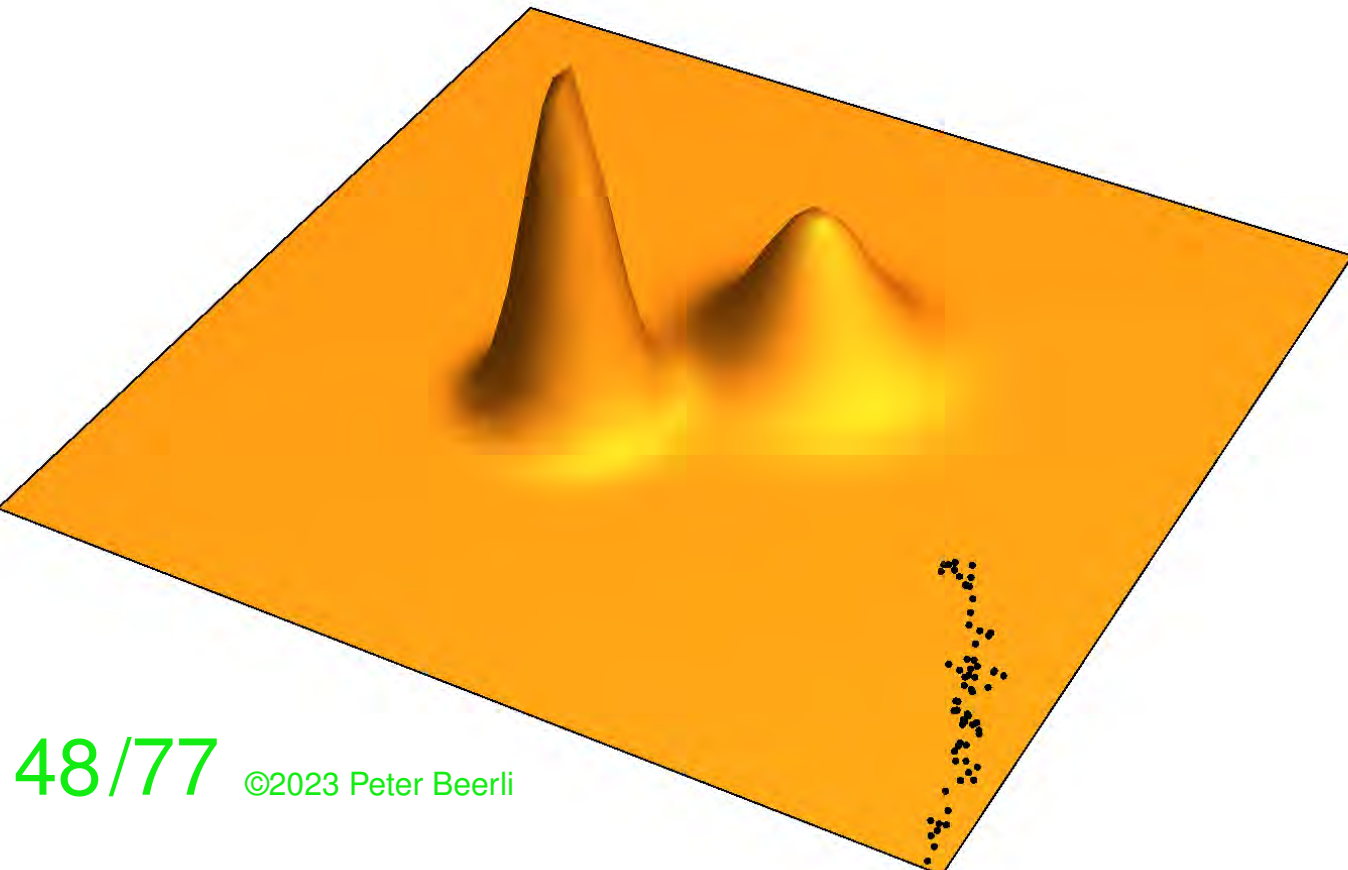
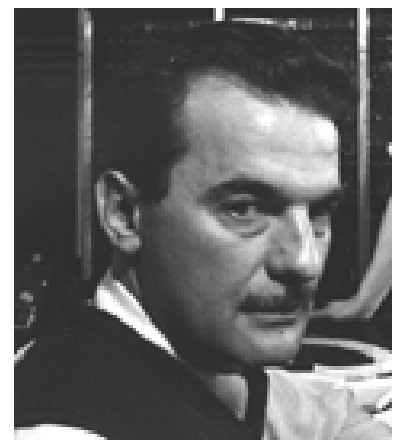
Metropolis-Hastings algorithm



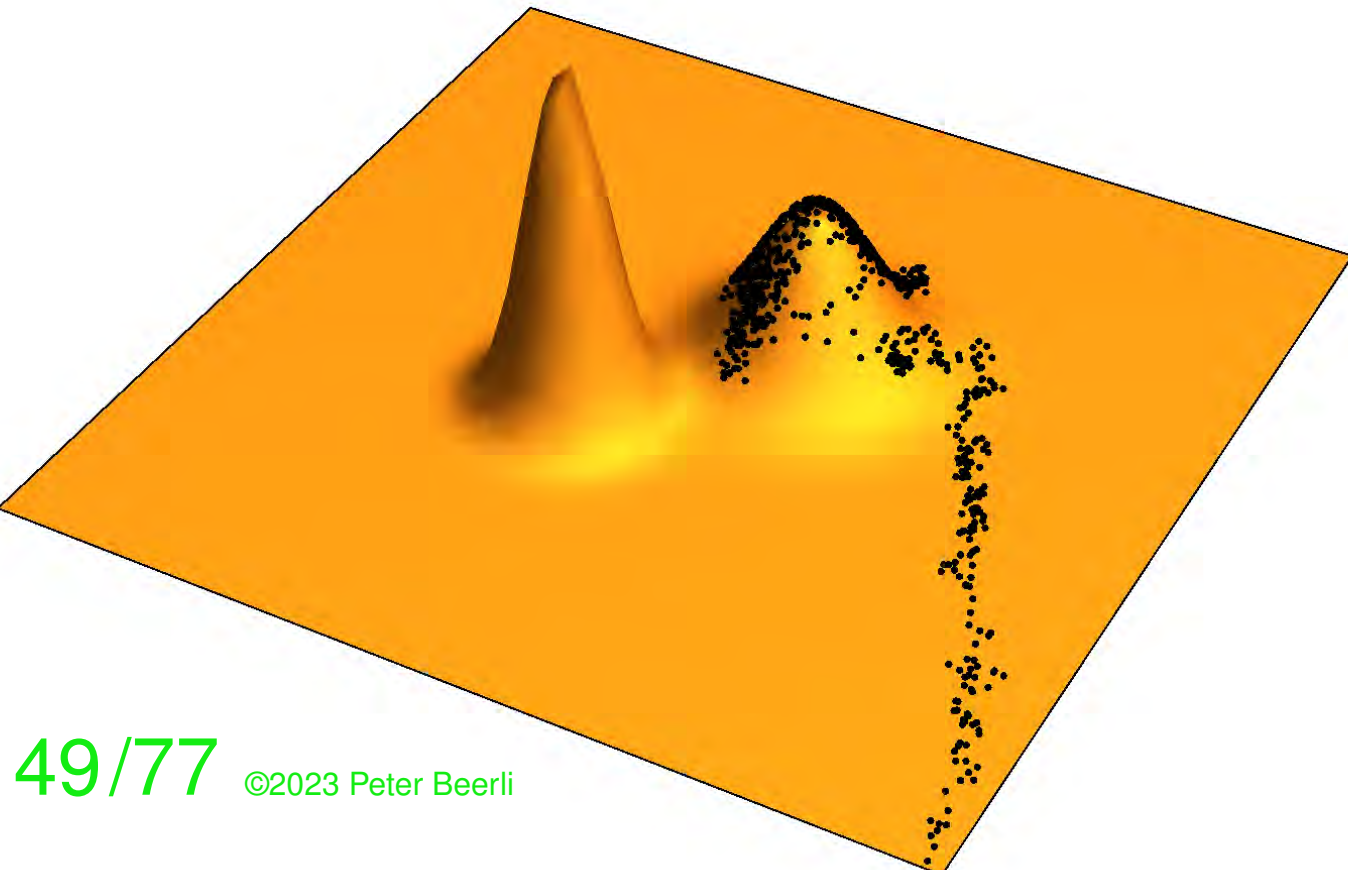
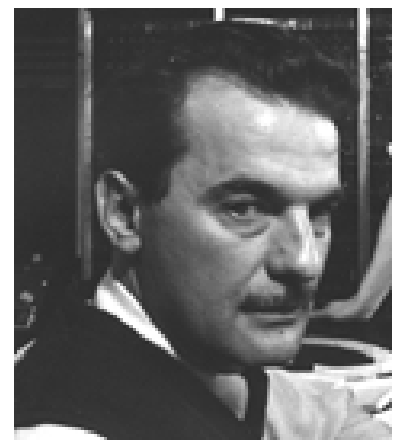
Metropolis-Hastings algorithm



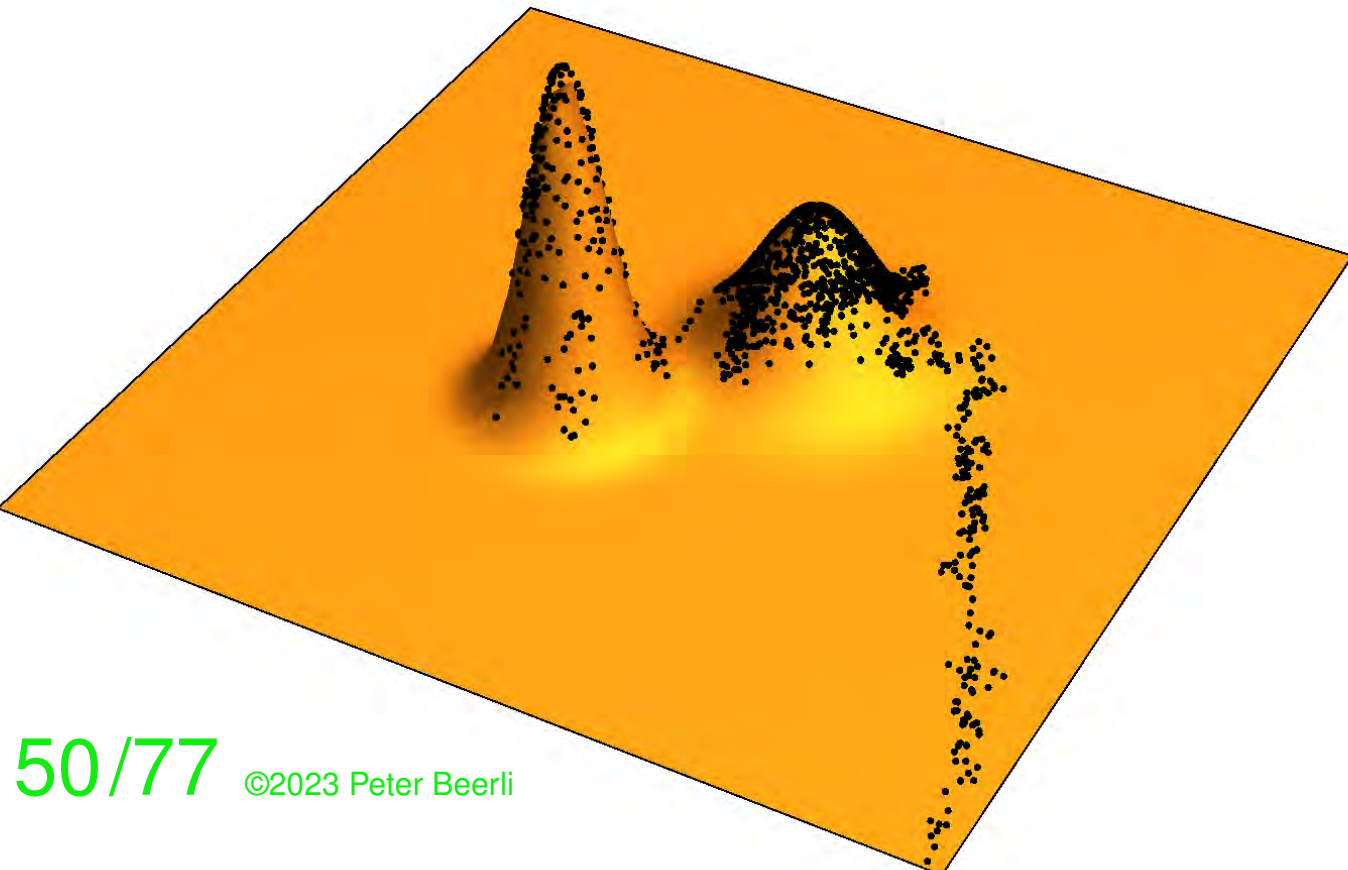
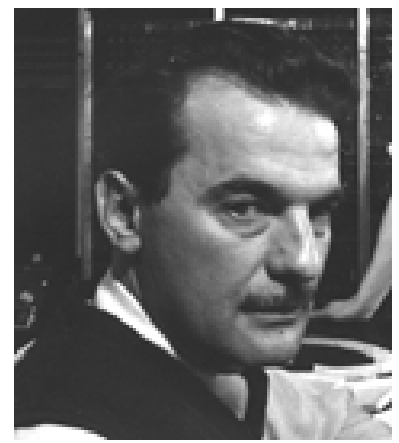
Metropolis-Hastings algorithm



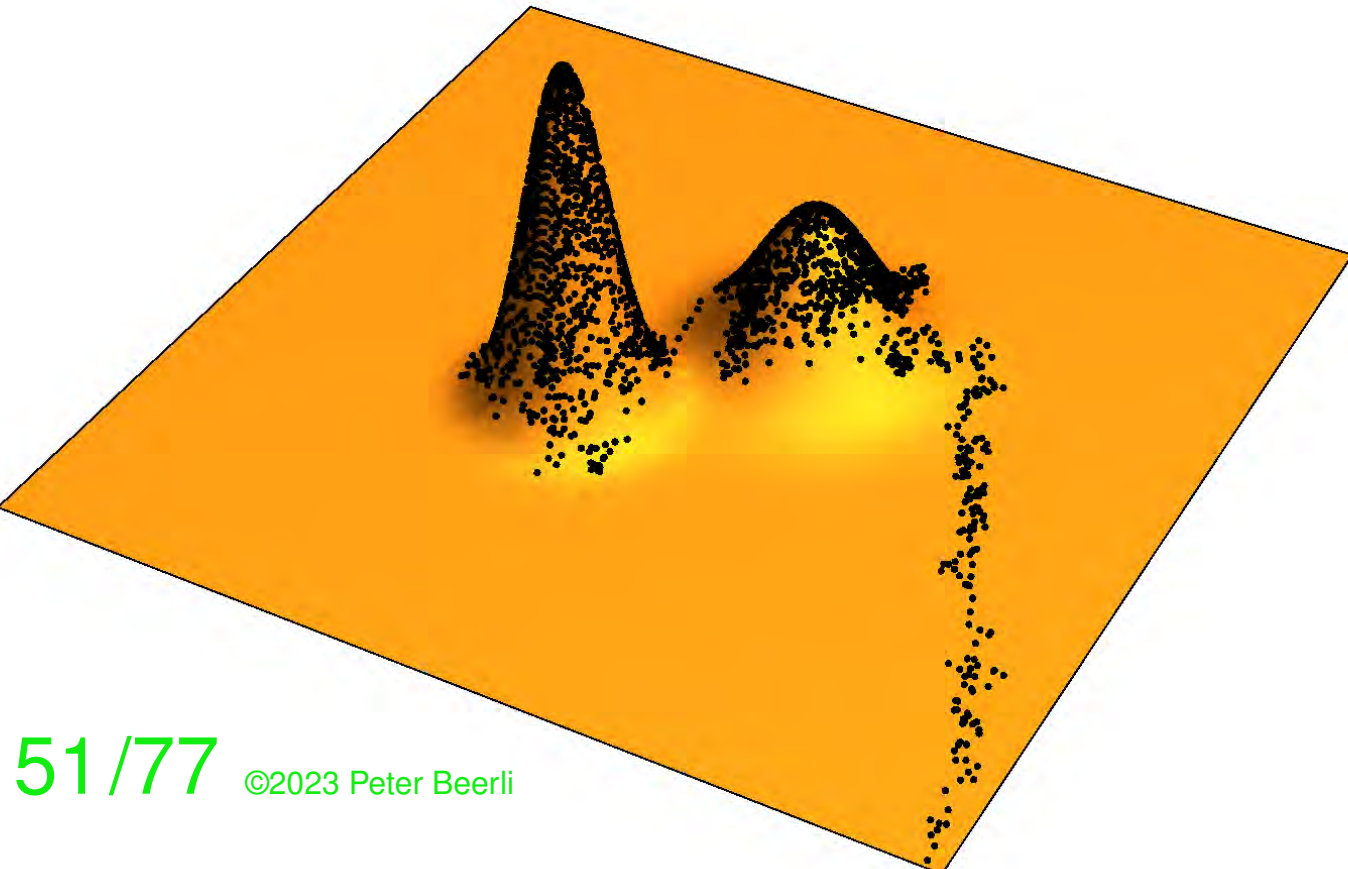
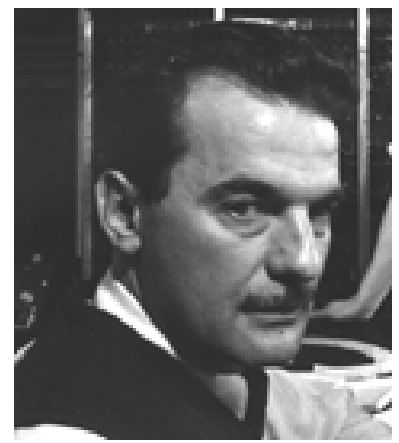
Metropolis-Hastings algorithm



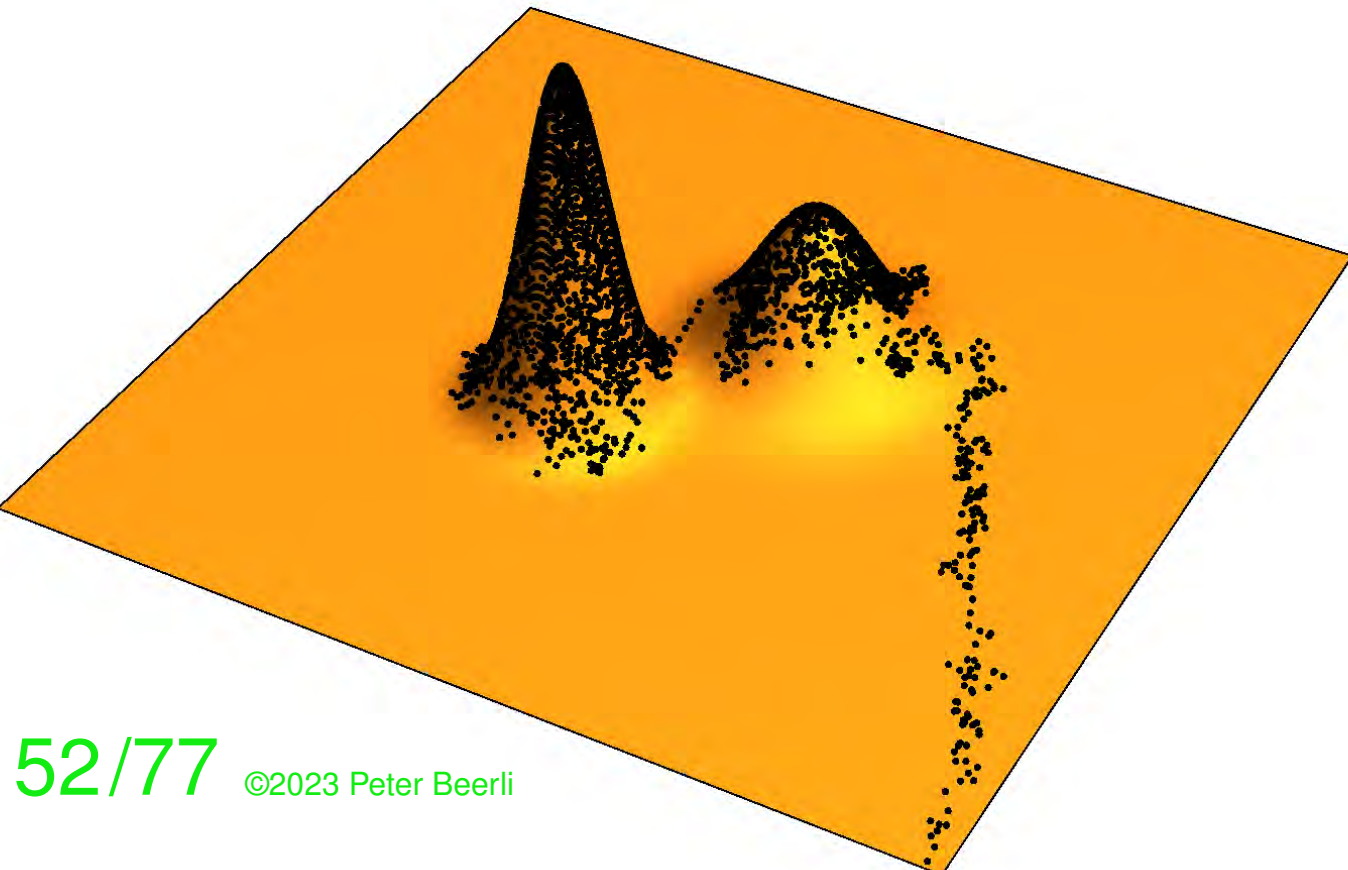
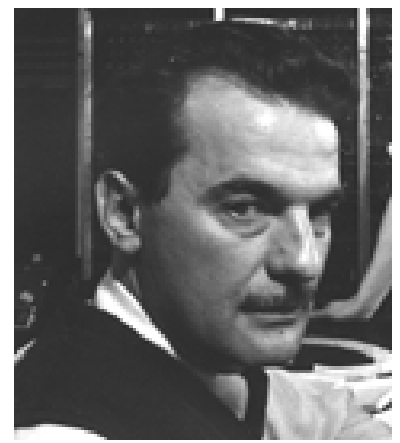
Metropolis-Hastings algorithm



Metropolis-Hastings algorithm



Metropolis-Hastings algorithm



So many models – so little time



Gene flow

Neanderthal

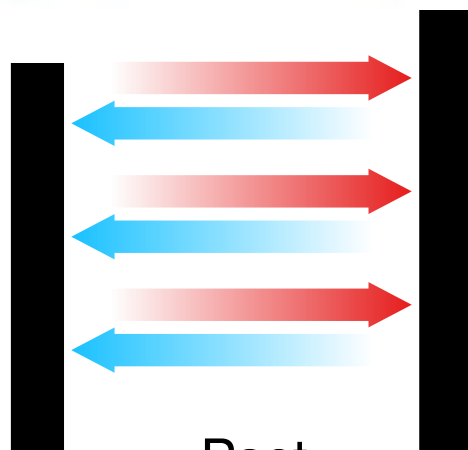


-30,000 years

'Modern' human



Present



Past

Divergence and Gene flow

Neanderthal

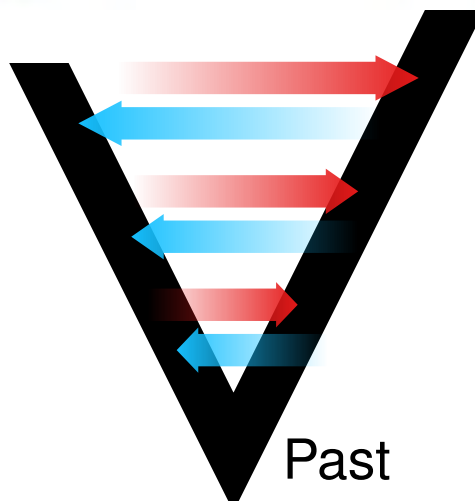


-30,000 years

'Modern' human

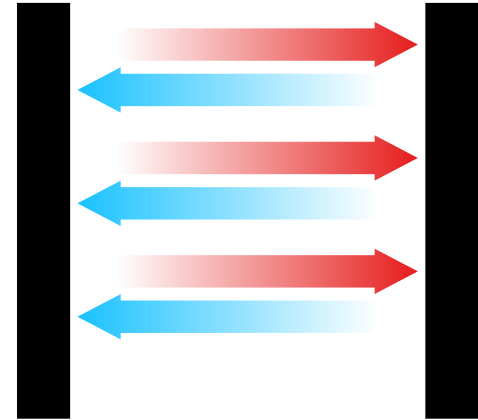
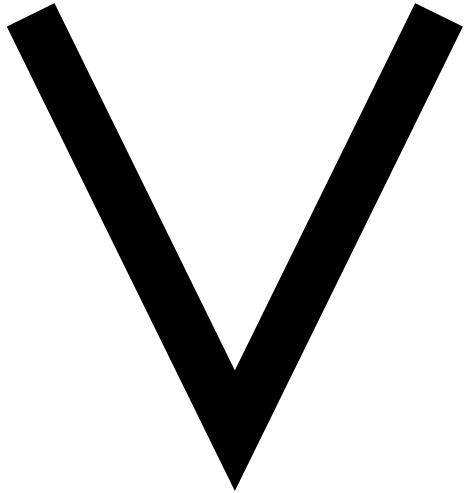


Present

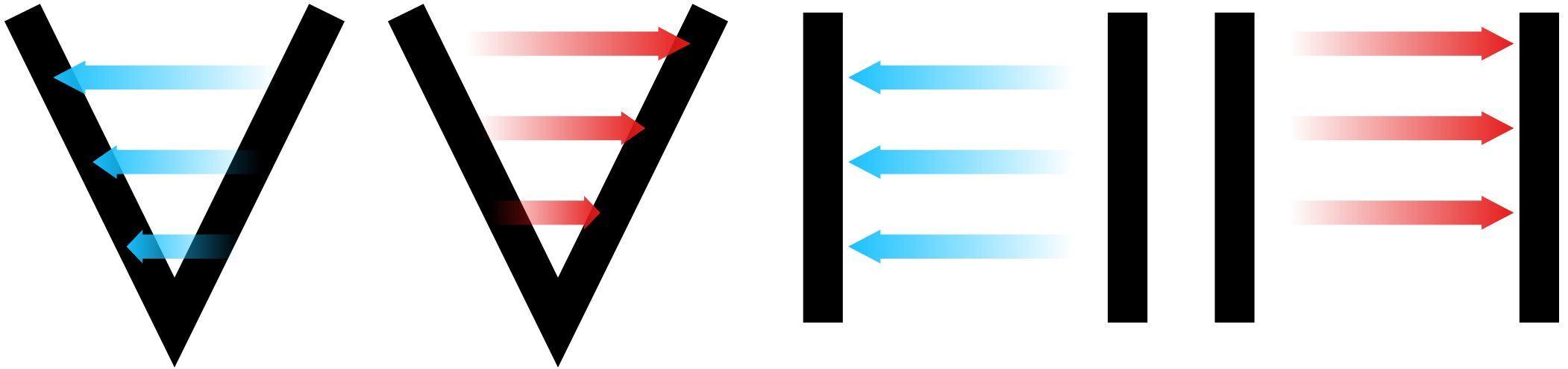


Past

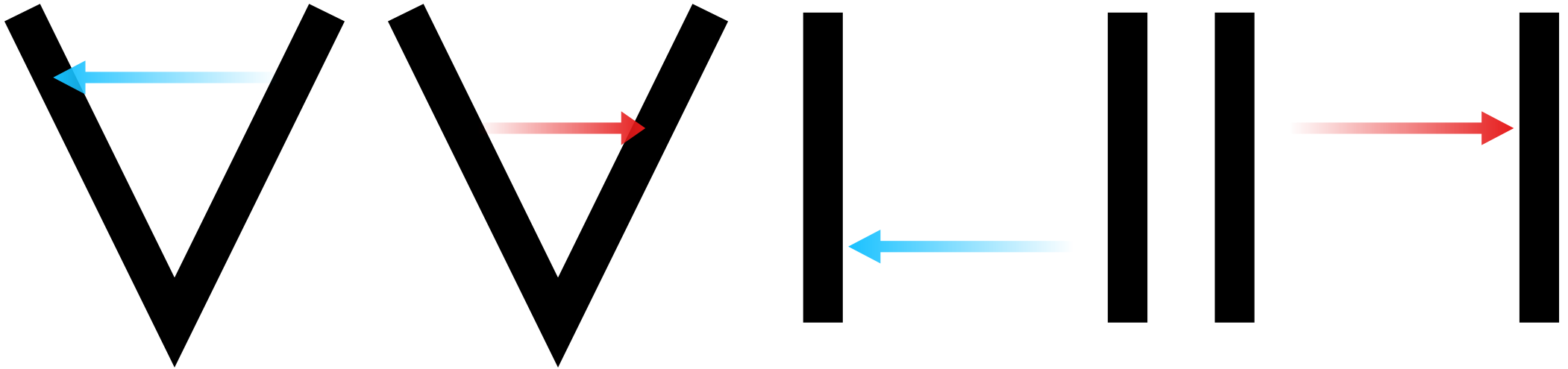
Different structural models



More different structural models



Even more different structural models



Model comparison

With a criterium such as likelihood we can compare nested models. Commonly we use a likelihood ratio test (LRT) or Akaike's information criterion (AIC) to establish whether phylogenetic trees are statistically different or mutation models have an effect on the outcome, etc.

Kass and Raftery (1995) popularized the [Bayes Factor](#) as a Bayesian alternative to the LRT.

Bayesian inference

$$P(A|B) = \frac{P(B|A)P(A)}{P(B)}$$

Bayes factor

Theoretically, we can calculate the posterior probability density of the model

$$p(M_1|X) = \frac{p(M_1)p(X|M_1)}{p(X)}$$

Bayes factor

Theoretically, we can calculate the posterior probability density of the model 1 and model 2

$$p(M_1|X) = \frac{p(M_1)p(X|M_1)}{p(X)}$$

$$p(M_2|X) = \frac{p(M_2)p(X|M_1)}{p(X)}$$

Bayes factor

Theoretically, we can calculate the posterior probability density of the model 1 and model 2

$$\frac{p(M_1|X)}{p(M_2|X)} = \frac{\frac{p(M_1)p(X|M_1)}{p(X)}}{\frac{p(M_2)p(X|M_2)}{p(X)}}$$

Bayes factor

We could look at the **posterior odds ratio** or equivalently the **Bayes factors**.

$$\frac{p(M_1|X)}{p(M_2|X)} = \frac{p(M_1)}{p(M_2)} \times \frac{p(X|M_1)}{p(X|M_2)}$$

$$\text{BF} = \frac{p(X|M_1)}{p(X|M_2)} \quad \text{LBF} = 2 \ln \text{BF} = 2 \ln \left(\frac{p(X|M_1)}{p(X|M_2)} \right)$$

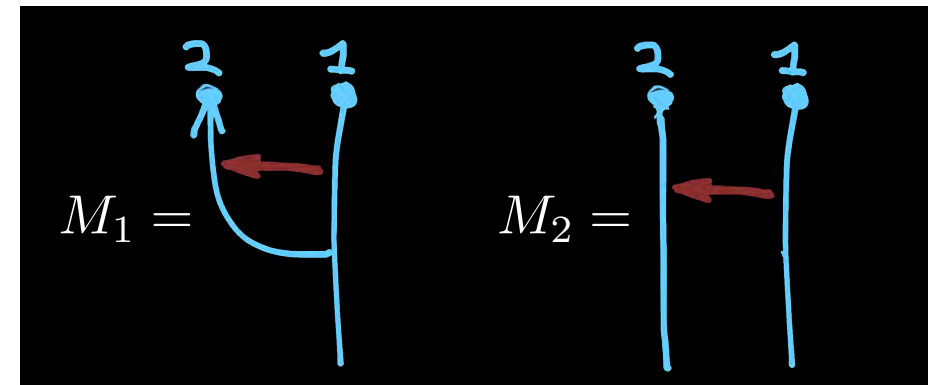
Bayes factor

$$\text{BF} = \frac{p(X|M_1)}{p(X|M_2)} \quad \text{LBF} = 2 \ln \text{BF} = 2 \ln \left(\frac{p(X|M_1)}{p(X|M_2)} \right)$$

The magnitude of BF gives us evidence against or for hypothesis M_2

$$\text{LBF} = 2 \ln \text{BF} = z \quad \begin{cases} 0 < |z| < 2 & \text{No real difference} \\ 2 < |z| < 6 & \text{Positive} \\ 6 < |z| < 10 & \text{Strong} \\ |z| > 10 & \text{Very strong} \end{cases}$$

Bayes factor example



$$\text{LBF} = 2 \ln \text{BF} = 2 \ln \left(\frac{p(X|M_1)}{p(X|M_2)} \right) = 2(-9638.69) - (-9641.01) = 4.64$$

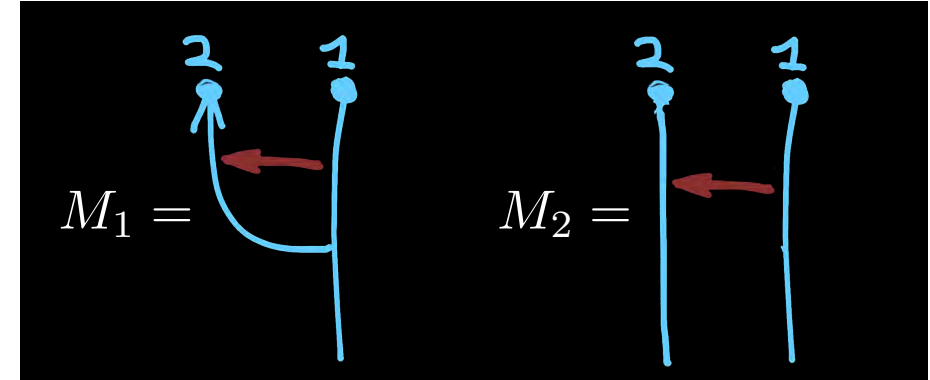
The magnitude of BF gives us evidence against or for hypothesis M_2

$$\text{LBF} = 2 \ln \text{BF} = z \quad \begin{cases} 0 < |z| < 2 & \text{No real difference} \\ 2 < |z| < 6 & \text{Positive} \\ 6 < |z| < 10 & \text{Strong} \\ |z| > 10 & \text{Very strong} \end{cases}$$

Posterior model probability

(example continued)

Instead of calculating the Bayes factor we could use the probability of all tested models M_i and use them as weights (cf. Burnham and Anderson, 1998)



$$p_i^* = \frac{p(X|M_i)}{\sum_j p(X|M_j)}, \quad \sum_i p_i^* = 1, \quad \ell_1 = -9638.61, \quad \ell_2 = -9641.01$$

$$p_1^* = \frac{\exp(\ell_1)}{\exp(\ell_1) + \exp(\ell_2)} = 0.911$$

$$p_2^* = \frac{\exp(\ell_2)}{\exp(\ell_1) + \exp(\ell_2)} = 0.089$$

Marginal likelihood

Typically, it is rather difficult to calculate the marginal likelihoods with good accuracy, because most often we only approximate the posterior distribution using Markov chain Monte Carlo (MCMC).

In MCMC we need to know only differences and therefore we typically do not need to calculate the denominator to calculate the Posterior distribution $p(\Theta|X)$:

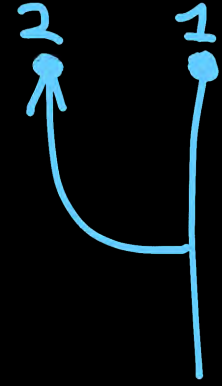
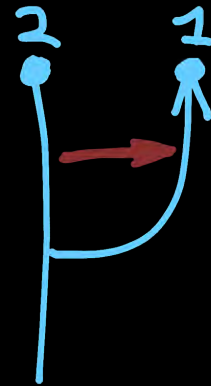
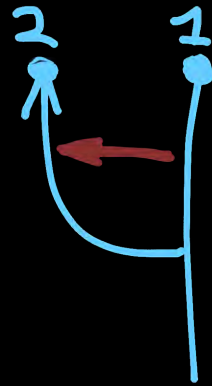
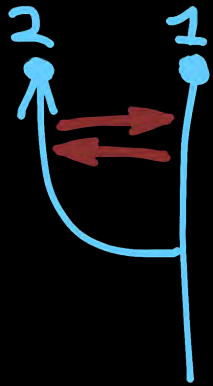
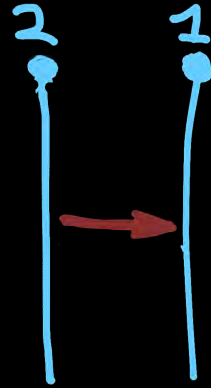
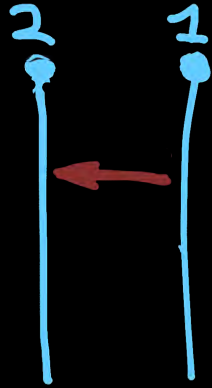
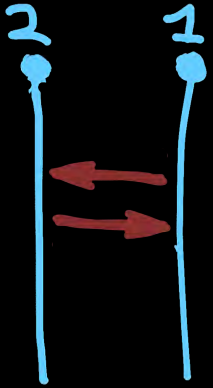
$$p(\Theta|X, M) = \frac{p(\Theta)p(X|\Theta)}{p(X|M)} = \frac{p(\Theta)p(X|\Theta)}{\int_{\Theta} p(\Theta)p(X|\Theta)d\Theta}$$

where $p(X|M)$ is the marginal likelihood, **which we need for our model selection!**

Estimation of the marginal likelihood

- ◆ Harmonic mean estimator [Kass and Raftery 1995]: method is easy and used in many programs, results are biased and overestimate the marginal likelihood, variance of estimates can be very large.
- ◆ Thermodynamic integration (Path sampling) [Gelman and Meng 1997, Lartillot et al. 2006]: method is tedious to compute because several MCMC chains are needed. Results are accurate and reproducible with small variance when MCMC runs were run long enough.
- ◆ Stepping stone approach (Xie et al. 2011)

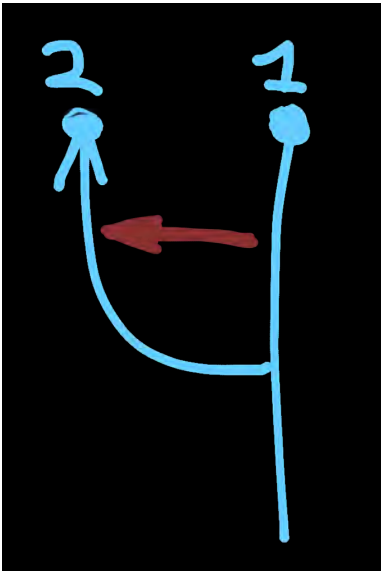
Population models



Simulated data

Two loci simulated from model x0Dx:

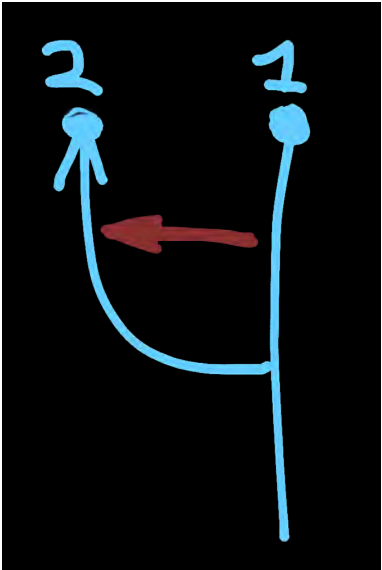
Model	Log(mL)	LBF*	Model-probability
1: xxxx:	-9662.42	-23.73	0.0000
2: xDxx:	-9661.98	-23.29	0.0000
3: xxDx:	-9661.52	-22.83	0.0000
4: xd0x:	-9656.51	-17.82	0.0000
5: xD0x:	-9649.33	-10.64	0.0000
6: xx0x:	-9648.93	-10.24	0.0000
7: x0dx:	-9641.77	-3.08	0.0402
8: x0xx:	-9641.01	-2.32	0.0859
9: x0Dx:	-9638.69	0.00	0.8739



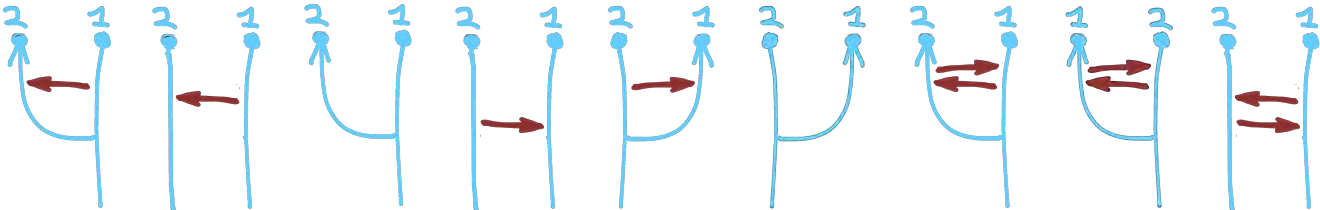
Simulated data

Two loci simulated from model x0Dx:

Model	Log(mL)	LBF*	Model-probability
1: xxxx:	-9662.42	-23.73	0.0000
2: xDxx:	-9661.98	-23.29	0.0000
3: xxDx:	-9661.52	-22.83	0.0000
4: xd0x:	-9656.51	-17.82	0.0000
5: xD0x:	-9649.33	-10.64	0.0000
6: xx0x:	-9648.93	-10.24	0.0000
7: x0dx:	-9641.77	-3.08	0.0402
8: x0xx:	-9641.01	-2.32	0.0859
9: x0Dx:	-9638.69	0.00	0.8739



Best

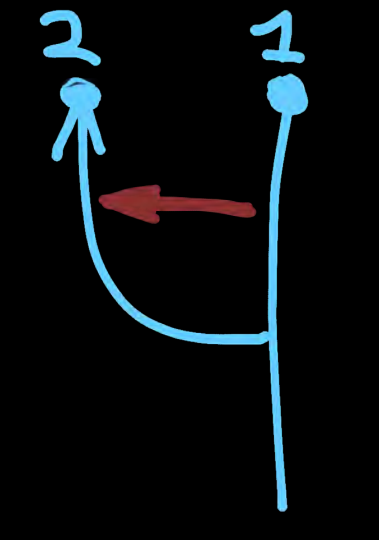


Worst

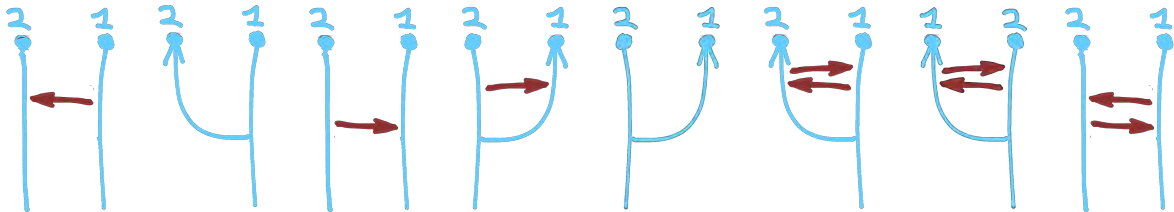
We did not include the correct model!

Two loci simulated from model x0Dx:

Model	Log(mL)	LBF*	Model-probability
1:xxxx:	-9662.42	-21.41	0.0000
2:xBxx:	-9661.98	-20.97	0.0000
3:xxBx:	-9661.52	-20.51	0.0000
4:xd0x:	-9656.51	-15.50	0.0000
5:xB0x:	-9649.33	-8.32	0.0002
6:xx0x:	-9648.93	-7.92	0.0002
7:x0dx:	-9641.77	-0.76	0.3185
8:x0xx:	-9641.01	0.00	0.6811



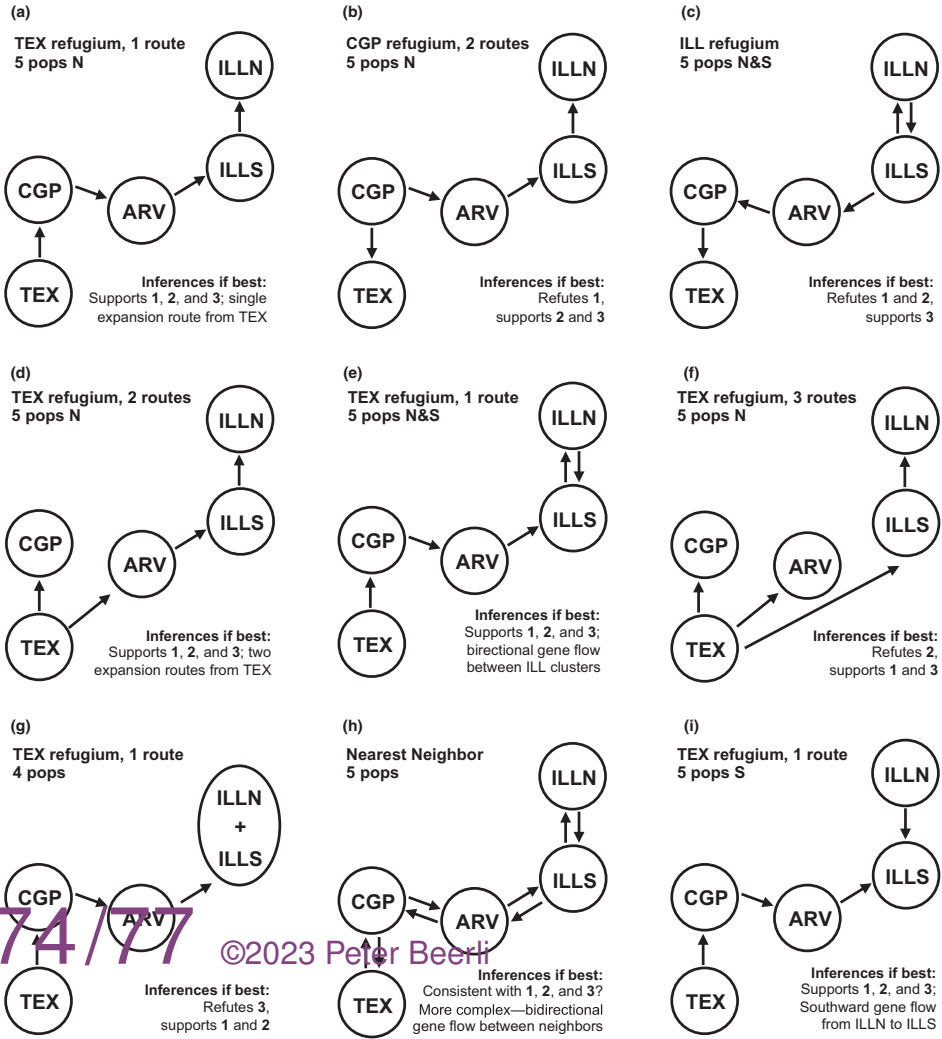
Best



Worst

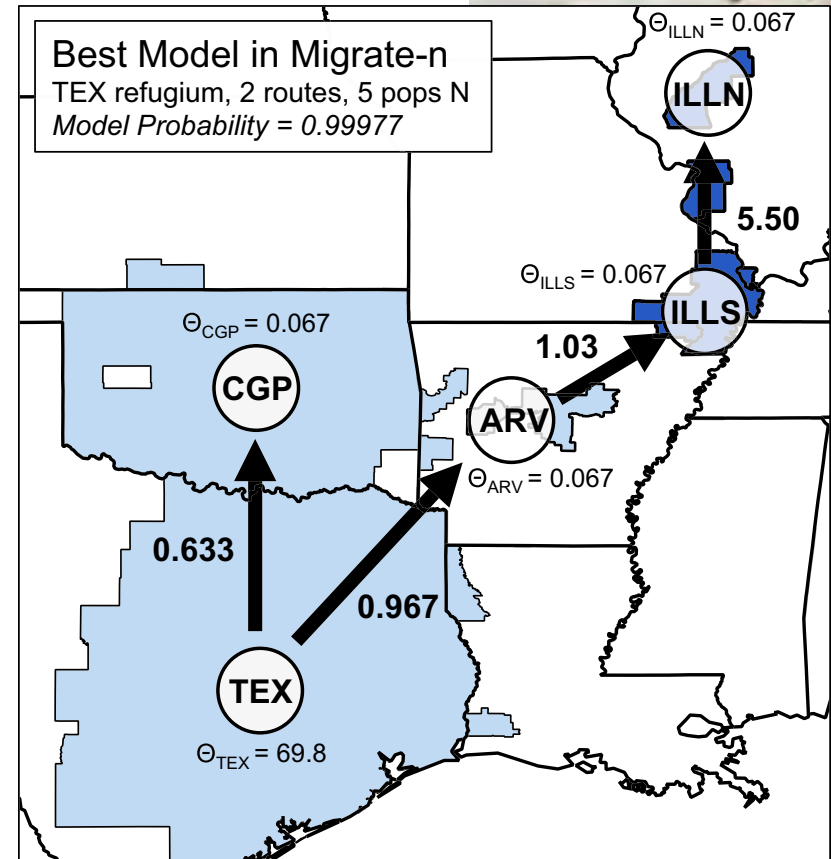
A real example

There is detectable genetic structure within *P. amnion* consistent with the disjunct range.



Frog picture: <http://mdc.mo.gov/discover-nature/field-guide>

Lisa N. Barrow, A. T. Bigelow, C. A. Phillips, and E. Moriarty Lemmon (2015) Phylogeographic inference using Bayesian model comparison across a fragmented chorus frog species complex. *Molecular Ecology*

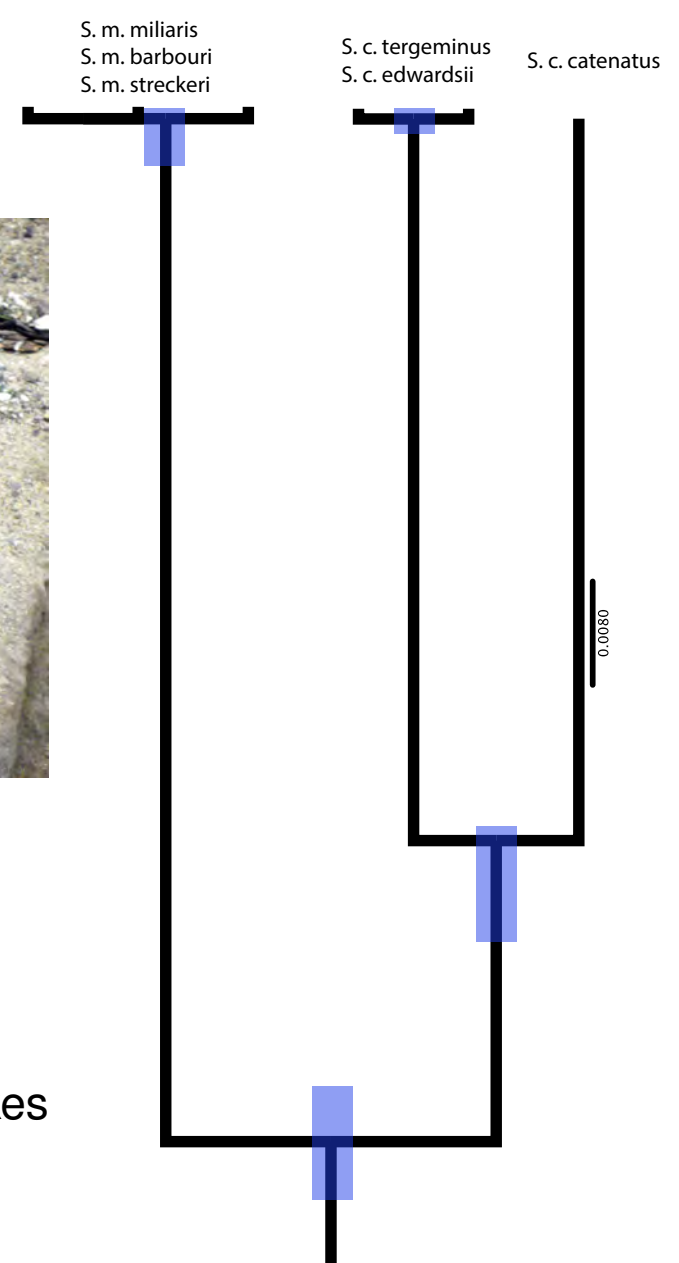


Population splitting



Model	Log(mL)	LBF	Model-probability
1: 3 species:	-15887.49	0.00	1.0000
2: 6 species:	-15961.95	-74.46	0.0000

Estimation of splitting dates of 6 subspecies of pygmy rattlesnakes
 Using MIGRATE (data from Kubatko et al. 2011)



Summary



- ◆ You may be surprised that your favored model does not win in a model comparison competition, but figuring out the model order leads oftentimes to new insights about the problem.
- ◆ Models by themselves are not true or wrong. BUT they may not fit your data well, OR they describe your data even when you “know” that the model is insufficient.

Thank you



Lucrezia Bieler



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Michal Palzcewski, <http://popgen.sc.fsu.edu>
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Somayeh Mashayekhi,
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